

An absolute Johnson noise thermometer

Luca Callegaro¹, Vincenzo D’Elia¹, Marco Pisani¹, and Alessio Pollarolo¹

¹INRIM - Istituto Nazionale di Ricerca Metrologica
Strada delle Cacce, 91 - 10135 Torino, Italy

Abstract. We developed an absolute Johnson noise thermometer (JNT), an instrument to measure the thermodynamic temperature of a sensing resistor, with traceability to voltage, resistance and frequency quantities. The temperature is measured in energy units, and can be converted to SI units (kelvin) with the accepted value of the Boltzmann constant k_B ; or, conversely, it can be employed to perform measurements at the triple point of water, and obtain a determination of k_B . The thermometer is composed of a correlation spectrum analyzer and a calibrated noise source, both constructed around commercial mixed-signal boards. The calibrator generates a pseudorandom noise, by digital synthesis and amplitude scaling with inductive voltage dividers; the signal spectrum is a frequency comb covering the measurement bandwidth. JNT measurements at room temperature are compatible with those of a standard platinum resistance thermometer within the combined uncertainty of $60 \mu\text{K K}^{-1}$. A path towards future improvements of JNT accuracy is also sketched.

1. Introduction

The accurate measurement of Johnson noise has been considered a method for determining the thermodynamic temperature, and the Boltzmann constant k_B , since its very first observation [1]. A resistor R , in thermodynamic equilibrium, generates a noise voltage $v(t)$ with the spectral power density[‡] $S_v^2 = 4R\mathcal{T}$, where \mathcal{T} is its thermodynamic temperature measured in energy units.

Within the International System of units, to the quantity temperature T a base unit is associated, the kelvin (K), defined by assigning the temperature of the triple point of water (TPW), $T_{\text{TPW}} = 273.16\text{K}$; the relation $\mathcal{T}_{\text{TPW}} = k_B T_{\text{TPW}}$ defines k_B . In an effort towards a possible redefinition of the kelvin, in 2005 the Consultative Committee for Thermometry (CCT) of the International Committee for Weights and Measures (CIPM) [2] recommended to "initiate and continue experiments to determine values of thermodynamic temperature and the Boltzmann constant".

Johnson noise thermometry experiments have the potential for such new determinations. A detailed analysis suggests [3] the possibility of achieving a k_B relative uncertainty of a few parts in 10^6 , comparable to estimated or forecasted uncertainties of other existing or proposed experiments [4].

In the following, we present a Johnson noise thermometer (JNT) which measures \mathcal{T} with traceability to national standards of ac voltage, resistance and frequency. If k_B is taken as given (in the following the CODATA 2006 adjustment [5, 6] will be employed) the JNT measurement outcome can be compared with an ITS-90 temperature T_{90} measurement taken as reference.

Presently, the JNT has been tested by performing measurements near room temperature. A measurement run at room temperature gives T in agreement with T_{90} within the combined relative measurement uncertainty around $60\mu\text{K K}^{-1}$. Several uncertainty contributions are related to the use of commercial instrumentation. In the future, purposely-built instruments under development will permit a significant accuracy improvement, and will open the possibility of employing the JNT for a new determination of k_B .

2. Absolute and relative measurements

The main difficulty in the development of an accurate JNT is the faintness of the Johnson noise, which must be amplified by a large factor ($10^4 - 10^6$). Noise added by front-end amplifiers has an amplitude comparable with that of the Johnson noise itself, but can be rejected with the correlation technique (see Ref. [7, par. 6.4] for a review, and [8] for an extended mathematical treatment of digital correlation). An adequate rejection requires a careful design of the correlator, and in particular of its front-end amplifiers [9, 10, 11]. The drawback of most effective amplifier designs criteria is a poor stability

[‡] The expression is accurate to one part in 10^7 at room temperature and frequency below 1 MHz.

of gain and frequency response. Hence, an automated in-line gain calibration subsystem has to be incorporated in the JNT.

We may call *relative* JNTs [7] those where the calibration signal is also given by Johnson noise of a resistor (the same, or a different one), placed at a known reference temperature, which is typically T_{TPW} . A relative JNT measures the ratio $\mathcal{T}/\mathcal{T}_{\text{TPW}} = T/T_{\text{TPW}}$.

An *absolute* JNT measures \mathcal{T} directly; therefore, the calibration signal has to be traceable to electromechanical SI units. Although in the past [3] a detailed proposal of an absolute JNT has been published, the only absolute JNT now in operation is at the National Institute of Standards and Technology (NIST) [12, 13, 14]. In NIST's JNT the calibration signal is generated by a synthesized pseudorandom voltage noise source based on pulse-driven Josephson junction arrays. The calibration signal amplitude is thus directly linked to the Josephson fundamental constant K_J , and the driving frequency of the Josephson array.

In the setup here presented, the calibration signal is generated with a commercial digital-to-analog (DAC) board, measured with an ac rms thermal voltmeter, and scaled in amplitude with a chain of electromagnetic voltage dividers (see Sec. 4.4).

3. Overview of the implementation

The block schematics of the JNT is shown in Fig. 1.

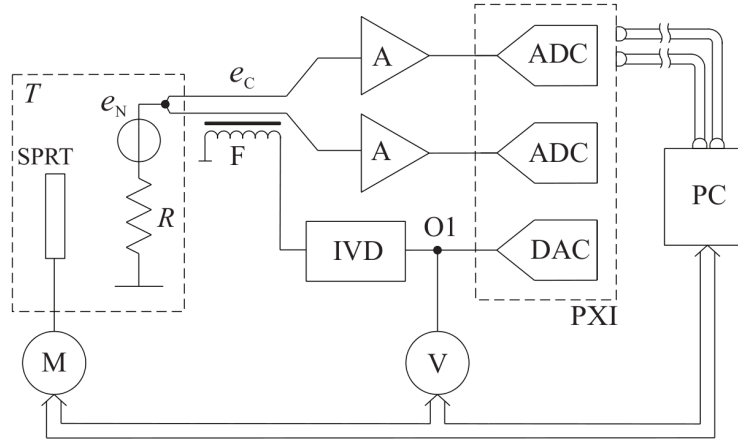


Figure 1. Block schematics of the JNT, see text for details.

The probe resistor R , generating the Johnson noise e_N , is at temperature T , measured with a standard platinum resistance thermometer SPRT and a resistance meter M . The signal e_N is acquired by two identical acquisition channels in parallel, each one composed of an amplifier A and an analog-to-digital converter ADC . Resulting digital codes are transmitted by an optical fibre interface to the processing computer PC , which implements a digital correlation spectrum analyzer algorithm.

The signal e_C is employed to periodically calibrate the analyzer gain, and injected in series with e_N . e_C is a pseudorandom noise, with the same bandwidth B of the measurement. It is generated by PC and a digital-to-analog converter DAC (also connected with the optical link). The waveform is measured by a voltmeter V, and reduced in amplitude by inductive voltage dividers IVD and an injection feedthrough transformer F. The measurements of V and M are acquired by PC through an IEEE-488 interface bus.

4. Details of the implementation

4.1. Probe resistor

The probe is a single resistor R , enclosed in a cylindrical screen and connected to the amplifiers A by a shielded four-wire cable. Presently a Vishay mod. VSR thick film resistor, having a nominal value of $1\text{ k}\Omega$, is employed. R is calibrated in dc regime, but a relative frequency deviation lower than 5×10^{-6} up to 10 kHz is expected [15].

4.2. Amplifiers

Amplifiers A are identical; each one is composed by two stages, giving an overall gain of $\approx 31\,000$. The first stage (see Ref. [16] for details) is a pseudo-differential, cascode FET amplifier in an open-loop configuration [11]. Its equivalent input voltage noise is $\approx 0.8\text{ nV}/\sqrt{\text{Hz}}$, and the bias current is $\approx 2 - 3\text{ pA}$; the gain flatness is better than 1 dB over 1 MHz bandwidth. It is battery-powered (by separate battery packs for each channel to avoid residual correlations due to limited power-supply rejection ratio), and electrostatically shielded. Both first stages are placed in a μ metal box which acts as a magnetic shield. A second conventional op amp stage, working also as a rough bandpass filter and having with a separate power supply, follows.

4.3. Spectrum analyzer

The ADCs are those of a commercial board (National Instruments mod. 4462: 24 bit resolution, 204.8 kHz maximum sampling frequency, synchronous sampling of the channels), embedded in a PXI rack. Codes are acquired continuously and transmitted by an optical fibre link interface (National Instruments mod. 8336) to PC, where a digital cross-correlation algorithm based on fast-Fourier transform computes and averages spectra $C(f_k)$ having up to 2^{17} discrete frequency points f_k . Acquisition and computation are performed in parallel to optimize the measurement time.

4.4. Calibration

The calibration subsystem is shown in Fig. 2.

A commercial DAC board (National Instrument mod. 6733 board, 16 bit resolution, 1 MHz maximum sampling frequency, synchronized with the spectrum analyzer ADCs

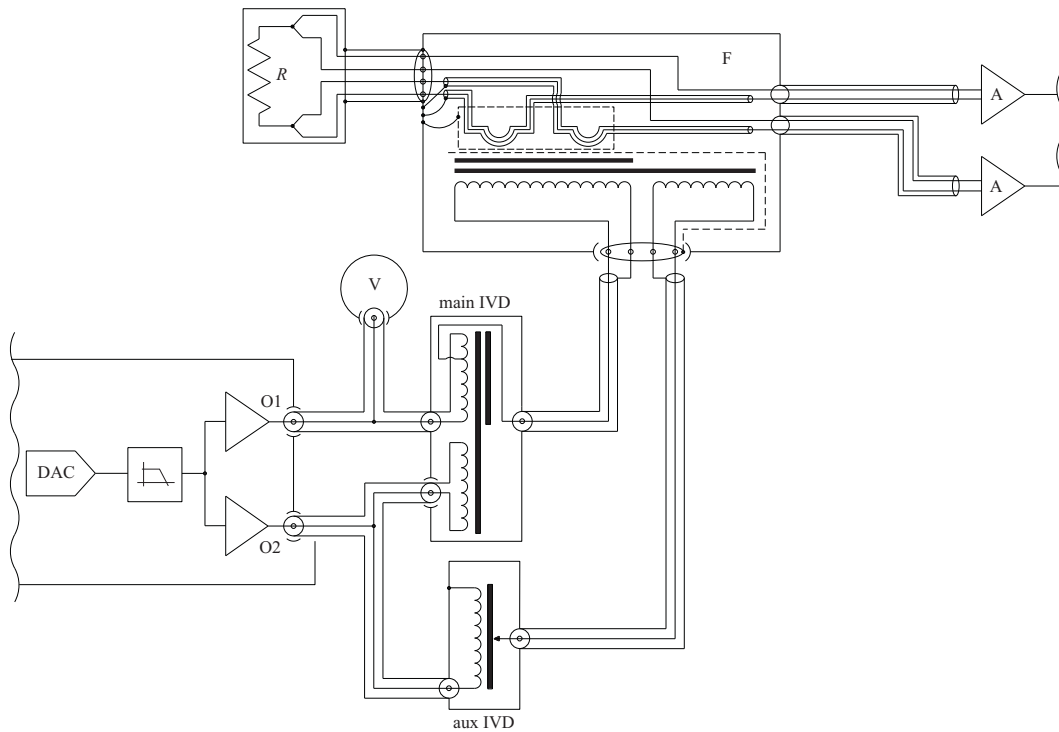


Figure 2. Detailed schematics of the calibration subsystem, see text for details.

and embedded in the same PXI rack) generates the calibration waveform, which goes through an anti-alias filter (a 6-pole analog Butterworth lowpass filter with 30 kHz bandwidth), and is buffered by two amplifiers with outputs O1 and O2 (each amplifier is provided with dc output restoration circuit [17] to drive electromagnetic devices).

The signal is generated at an amplitude of ≈ 300 mV. One of the outputs (O1) is measured with a calibrated thermal voltmeter V: presently, a Fluke mod. 8506A voltmeter is employed. Because of its limited accuracy and stability, the 8506A reading is compared, immediately before and after each experiment, with the reading of a Fluke mod. 5790A ac measurement standard, traceable to the national standard of ac voltage§.

After generation, the calibration waveform is scaled in amplitude (presently, by a factor of 12 000) by two divider stages in cascade:

- a block of two inductive voltage dividers (IVD), both set at 0.01 ratio. The main IVD is a fixed two-stage divider; its magnetizing winding is energized by O2, and the ratio winding by O1 (the same measured by V). The auxiliary IVD is a commercial 7-decade divider (Electro Scientific Instruments ESI mod. DT72) also energized by O2;
- a two-stage feedthrough transformer F. Its magnetizing winding is energized by the auxiliary IVD output, while the primary winding by the main IVD output. Both windings have 120 turns. Two single-turn secondary windings (wound with opposite

§ Unfortunately, the 5790A has a periodically fluctuating input impedance [18] which causes glitches in the acquisition, and cannot be directly employed during the measurement.

polarities) inject the calibration signal e_C in series with each connection of R to the amplifiers. The two-stage technique not only improves the ratio accuracy but also reduces the burden of F on the main IVD.

Both main IVD and F ratios are presently not calibrated, and the nominal turn ratio is employed in data processing.

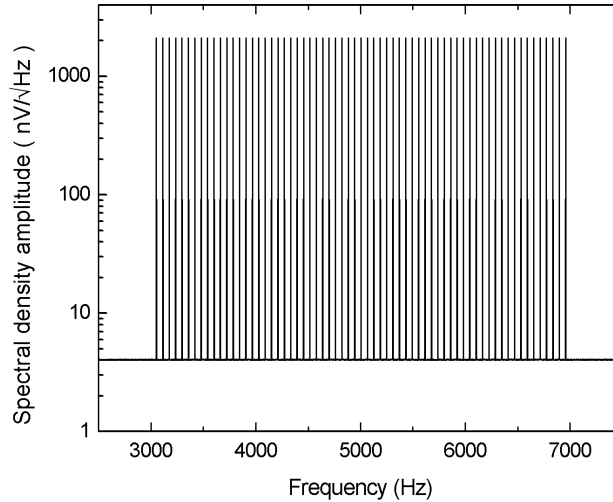


Figure 3. The calibration signal e_C for a bandwidth $B = 3 - 7$ kHz. The baseline is the Johnson noise e_N .

The calibration signal e_C is a pseudorandom noise, continuously recycled, having the power spectrum of an uniform frequency comb (see Fig. 3). The acquisition time for a single spectrum analyzer sweep is a multiple of the repetition period of the calibration signal, and since ADC and DAC sampling rates are commensurate and derived from the same clock, no spectral leakage occurs in the spectrum analyzer output.

At variance with NIST calibration waveform, whose comb covers the entire bandpass of the analyzer, e_C is band-limited: the comb frequencies cover uniformly the chosen measurement bandwidth B . The sinewave amplitudes are carefully adjusted in order to have a flat comb (relative deviations from the average amplitude better than 1×10^{-3}) at the output of the main IVD. Since the sinewaves have a relative phase chosen at random, e_C has an approximate Gaussian distribution of amplitudes.

4.5. Thermometry

Resistor R is at the moment not thermostated, but simply kept in an isothermal equalization block at room temperature. Temperature T_{90} is measured with a $100\,\Omega$ standard platinum resistance thermometer (SPRT), a Minco mod. S1060-2, calibrated at the fixed points of the ITS-90, as maintained at INRIM [19]. The meter M measuring

the SPRT is presently a Agilent Tech. mod 3458A, option 002, whose calibration is traceable to Italian standard of dc resistance.

5. Measurement procedure

The measurement consists of n repeated cycles, labeled $j = 1 \dots n$, each one composed of two phases:

- measurement of Johnson noise spectrum $N^j(f_k)$ (the average of m_N sweeps). Temperature T_{90}^j is also measured during this phase;
- measurement of calibration spectrum $C^j(f_k)$ (the average of m_C sweeps). Calibration voltage V^j is also measured during this phase.

In the present setup (and, correspondingly, Eq. 1) we chose to inject e_C in series with e_N during the calibration phase, at variance with the standard method of alternately measuring e_C and e_N . The advantage is a simplification in the layout, since no low-signal switching device is required, and electro-magnetic interferences (EMI) are easier to be kept under control. Moreover, impedance matching between the two phases is automatically achieved. On the other hand, the effect of possible spectrum analyzer nonlinearities has to be carefully considered [13].

The measurement model is:

$$\begin{aligned} G^j &= \frac{1}{V^j} \left\{ \Delta f \sum_{f_k \in B} [C^j(f_k) - N^j(f_k)] \right\}^{1/2}, \\ \mathcal{T}^j &= \frac{1}{4R(G^j)^2} \sum_{f_k \in B} N^j(f_k), \\ \Delta T^j &= k_B^{-1} \mathcal{T}^j - T_{90}^j, \quad \delta^j = \frac{\Delta T^j}{T_{90}^j}; \end{aligned} \tag{1}$$

where G^j is the equivalent gain of the cross-correlator during cycle j (average over the bandwidth B of the calibration signal); and $\Delta f = f_{k+1} - f_k$ is the frequency bin corresponding to each f_k . ΔT^j is the deviation of JNT reading \mathcal{T}^j with respect to the reference temperature T_{90}^j , and δ^j the same deviation expressed in relative terms.

6. Results

As an example of results, the following refers to a continuous acquisition run (the parameters of the acquisition are: $n = 1200$ cycles, each of 2^{17} points at 200 kHz sampling frequency, $m_N = 200$, $m_C = 50$, $B = 3 - 7$ kHz; the calibration signal has a length of 2^{14} codes with 500 kHz sampling rate). Total measurement time is 2.3×10^5 s (about 2.7 d).

A typical spectrum of $N(f_k)$ (averaged over j), and the corresponding autospectra of the two channels (rescaled with the same G_j), are shown in Fig. 4.

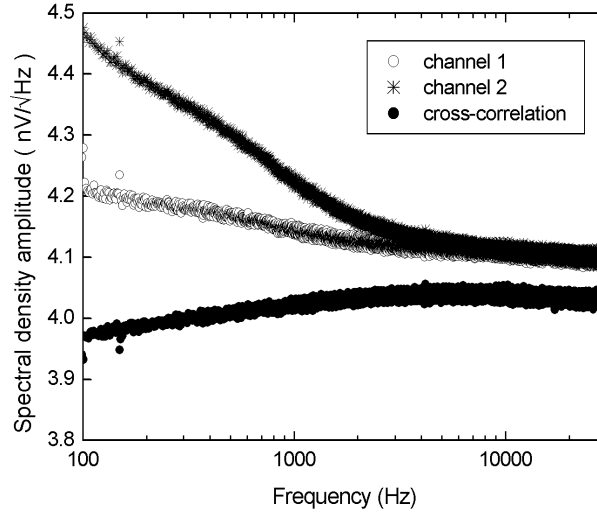


Figure 4. Amplitude spectra of the cross-correlation signal $N(f_k)$ and of the auto-correlation of the two spectrum analyzer acquisition channels separately. The flicker noise of A is apparent in the autospectra. The shape of $N(f_k)$ is slightly convex because of the bandpass filtering in the second stage of A.

For this experimental run, the relative deviations δ^j have a mean $\delta = -33 \mu\text{K K}^{-1}$ with a standard deviation $\sigma_\delta = 40 \mu\text{K K}^{-1}$. Such experimental value for σ_δ is near (+24%) the theoretical prediction for the Type A uncertainty of a measurement performed with an ideal absolute thermometer^{||} measuring over the same bandwidth B for same total time τ . More interestingly, σ_δ is somewhat *lower* (−14%) than the theoretical prediction for an ideal *relative* noise thermometer, if τ includes the time required for calibration with a known reference temperature; see Ref. [8] for an extensive explanation.

Fig. 5 shows these same conclusions in graphical form, but when Allan standard deviations are compared; the noise of δ is still approximately white, therefore the JNT Type A uncertainty is at the moment limited only by the acquisition time. The time for a continuous measurement run is in turn limited by battery charge (the run here presented is close to this limit) but the results of several runs can be averaged together.

An interesting performance test [20] is the measurement, instead of the noise e_N of the resistor R , of two independent noises e_{N1} and e_{N2} generated by two resistors R_1 and R_2 , mounted in a probe having electrical properties similar to that of R . An ideal spectrum analyzer outcome would be a null spectrum at any frequency; the spectrum measured gives the magnitude of the systematic errors due to undesired residual correlation effects. In the present setup, the residual correlation has a quadratic frequency dependence, which integrated on B give a systematic deviation lower than $10 \mu\text{K K}^{-1}$. However, the test does not rule out the existence of all residual correlations

^{||} That is, having noiseless amplifiers and an *a priori* known and stable gain.

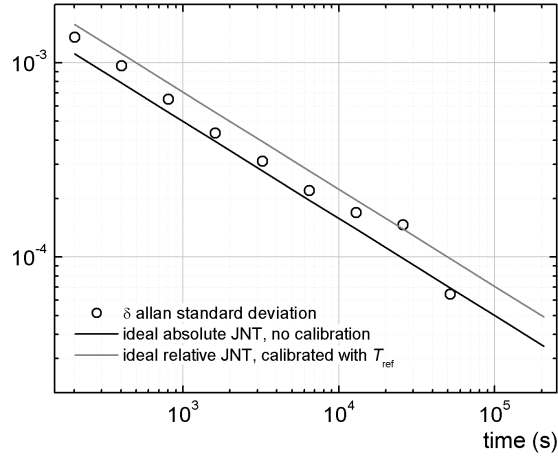


Figure 5. Allan standard deviation of the JNT error $\delta_j = \Delta T^j / T_{90}$, compared with the corresponding theoretical predictions for an ideal absolute thermometer and an ideal relative thermometer calibrated against a reference temperature T_{ref} .

[3, 9, 11] that could occur when a single resistor is measured.

Consistency tests for different run parameters (bandwidth B extension, sampling rate, R value, e_C/e_N ratio, choice of m_N and m_C , etc) require great experimentation effort, and will be conducted in a systematic way on a future version of the thermometer (see Sec. 8) for which we expect improved performances.

7. Uncertainty

The JNT uncertainty estimation includes a large number of terms. While some of them are related to well-established instrument properties and calibration techniques (thermometry, resistance and ac voltage measurement), others are matter of careful theoretical evaluations and ad-hoc experiments on acquisition chain of the thermometer [9, 10] and in particular of the properties of the input amplifiers [11]. Even the data processing algorithms may cause unexpected systematic errors, as has been very recently pointed out [8]. We didn't yet go through those hard tasks. Therefore, the uncertainty budget given in Tab. 1 for the relative reading error δ is intended only as a tool to identify further goals for improvement: some contributions are truly related to our JNT, others are simply taken from literature.

If the estimation of Tab. 1 is provisionally trusted, the relative difference between the JNT and resistance thermometer readings δ has an uncertainty $u(\delta) = 58 \mu\text{K K}^{-1}$, which main contribution come from the JNT reading. Such result can be compared with the recent estimate $u(\delta) = 25 \mu\text{K K}^{-1}$ of NIST absolute JNT at TPW [14], or with those of a number of (relative) acoustic thermometry results [21, 22], which consistently estimate $\delta = 12 \mu\text{K K}^{-1}$ with a relative uncertainty as low as $2 \mu\text{K K}^{-1}$ near the gallium fixed point ($\approx 303 \text{ K}$).

Table 1. Uncertainty budget for the thermometer relative error δ .

JNT uncertainty	Type	$\mu\text{K K}^{-1}$	mK	Note
Probe			(at 300 K)	
resistance calibration	B	4.9	1.5	Direct reading 3458A, 1 k Ω range, 90d cal
resistance drift	B	2.0	0.6	between recalibrations
Ac-dc correction	B	5.0	1.5	Ref. [14]
<u>Probe, total</u>	<u>B</u>	<u>7.3</u>	<u>2.2</u>	
Calibration signal				(x 2 sensitivity coefficient)
voltmeter calibration	B	25.4	7.6	5790A, 2.2V scale, 90d, over B
voltmeter stability	B	10.0	3.0	8506A drift
Main IVD ratio	B	5.8	1.7	Max error of 1×10^{-7} (referred to input) over B
Injection transformer ratio	B	20.8	6.2	Max error of 3×10^{-7} (referred to input) over B
Calibration, total	B	<u>34.8</u>	<u>10.4</u>	
Amplifiers and ADC				
EMI	B	10.0	3.0	Ref. [13]
Residual correlation	B	10.0	3.0	Experimental and Ref. [13]
Nonlinearity	B	5.0	1.5	Ref. [13]
Sampling frequency	B	1.4	0.4	clock specs
<u>Amplifiers and ADC, total</u>		<u>15.1</u>	<u>4.5</u>	
u_R, Type B, RSS	B	38.6	11.6	
u_R, Type A	A	40.4	12.1	2.3×10^5 s acquisition time
RSS		55.9	16.8	
Thermometry	Type	$\mu\text{K K}^{-1}$	mK	
SPRT calibration	B	1.0	0.3	Fixed points calibration ($U = 0.5$ mK @300 K)
Resistance meter	B	8.7	2.6	Direct reading 3458A, 100 Ω range, 90d cal
Self-heating	B	6.0	1.8	Estimate (not measured)
Immersion	B	1.5	0.5	at room temperature
Stability	B	5.0	1.5	over one cycle
<u>Thermometry, total</u>	<u>B</u>	<u>11.8</u>	<u>3.5</u>	
Comparison		$\mu\text{K K}^{-1}$	mK	
RSS		58.3	17.5	JNT and thermometry uncertainty

8. Conclusion and perspectives

Looking at Tab. 1, we see that a number of uncertainty contributions come from specifications of the commercial instruments employed or, more generally, from measurements for which primary metrology know-how provide better solutions. Therefore, there is room for improvements. We are working on:

- the development of a thermostat to perform measurements by varying T over a range that includes T_{TPW} [23];
- improvements in thermometry measurement setup with the implementation of a dc resistance bridge;
- the calibration of dividers over B under loading condition;
- improvements in the measurement of V^j with an automated ac-dc transfer measurement system based on a multijunction thermal converters [24];

- the increase in the measurement bandwidth to $B \approx 20$ kHz;
- larger battery packs, for an extended measurement time.

With these improvements, the measurement uncertainty should drop to the level of $10 \mu\text{K K}^{-1}$; a measurement at T_{TPW} will permit the determination of k_{B} with the same uncertainty.

Acknowledgments

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