

CHE384, From Data to Decisions: Measurement, Uncertainty, Analysis, and Modeling

Lecture 31

Total Regression, part 2

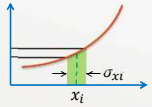
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Effective Variance Approximation

- We can simplify the regression for the case of **small** errors in x
 - Let $\hat{x}_i = x_i$
 - Define an **effective variance** in y using the model $\hat{y}_i = f(x_i)$



$$\sigma_{yi-eff}^2 = \sigma_{yi}^2 + \left(\frac{\partial f}{\partial x_i}\right)^2 \sigma_{xi}^2$$

- Use a weighted least-squares fit with these uncertainties
- Special case: $\sigma_{yi} = \sigma_{xi} = \text{constant}$

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Special Case: $\sigma_x = \sigma_y$

- The effective variance becomes

$$\sigma_{yi-eff}^2 = \sigma_y^2 \left[1 + \left(\frac{\partial f}{\partial x_i} \right)^2 \right]$$

- For a straight-line model, $\sigma_{yi-eff}^2 \propto 1 + \beta_1^2$ and our chi-square becomes

$$\chi^2 = \sum_{i=1}^n \left(\frac{y_i - \hat{y}_i}{\sqrt{1 + \beta_1^2}} \right)^2$$

- Called **Orthogonal Regression** (or orthogonal distance regression)

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Orthogonal Regression ($\sigma_x = \sigma_y$)

- The least-squares solution for this case is

$$b_1 = \frac{s_y^2 - s_x^2 + \sqrt{(s_y^2 - s_x^2)^2 + 4s_{xy}^2}}{2s_{xy}}$$

$$b_0 = \bar{y} - b_1 \bar{x}$$

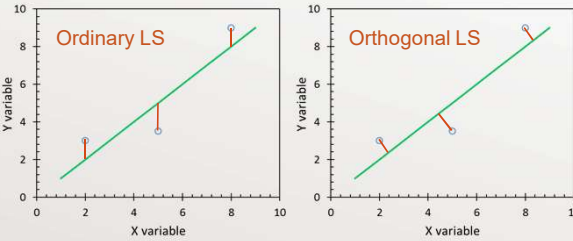
where s_x^2 = sample variance of x
 s_y^2 = sample variance of y
 s_{xy} = sample covariance of x and y

Standard error estimates will be discussed later

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Orthogonal Regression ($\sigma_x = \sigma_y$)

- Very useful for tool matching, calibration curves

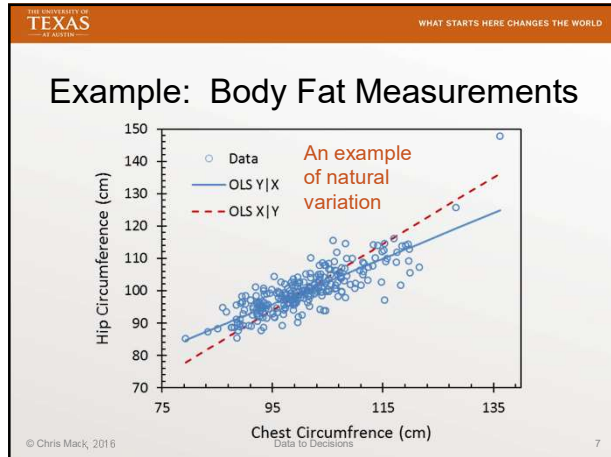


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Regression: Y vs. X or X vs. Y?

- Sometimes, it is not obvious that one variable is a response and the other variable is a predictor
 - Natural variation** (lurking variable): an unmeasured factor is controlling both variables
 - Calibration curve, tool matching
- How do we decide which variable to use as X (predictor) and which as Y (response)?
 - We often want a **symmetric** regression method

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Geometric Mean Regression

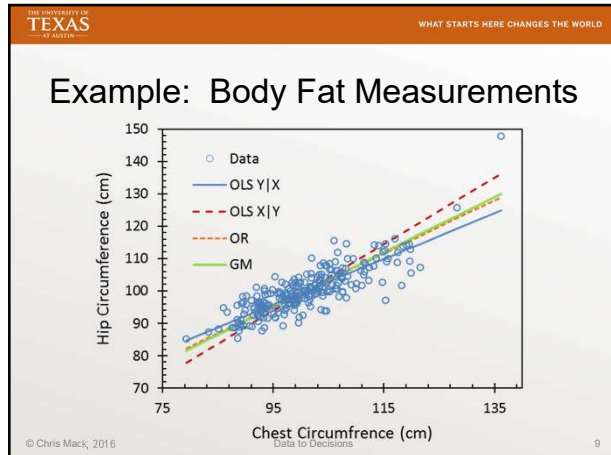
- Another proposal: estimate the slope as the **geometric mean** of the OLS slopes one obtains by regressing Y|X and X|Y
- After a small amount of algebra

$$b_0 = \bar{y} - b_1 \bar{x}$$

$$OLS(Y|X): b_1 = \frac{s_{xy}}{s_x^2}$$

$$GM: b_1 = \frac{s_y}{s_x}$$

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Method of Moments

- If we know σ_δ (the measurement error in x)
 - $x_i = \hat{x}_i + \delta_i$, $\delta \sim N(0, \sigma_\delta)$, $s_\delta = \text{known}$

Then
$$b_1 = \frac{b_{1(OLS)}}{1 - \left(\frac{s_\delta}{s_x}\right)^2}$$
 (only a reasonably good estimator for $n > 50$)

$$SE(b_1) = \frac{b_1}{\sqrt{n}} \sqrt{\frac{(s_x s_y)^2 + 2(b_1 s_\delta^2)^2}{(s_{xy})^2} - 1}$$

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Consistency

- An estimator is **consistent** if its bias goes to zero as the sample size goes to infinity
- Let $b_{1(OLS)}$ be the OLS estimator of the slope of a straight-line model. We can show that

$$\lim_{n \rightarrow \infty} b_{1(OLS)} = \frac{\beta_1}{1 + \left(\frac{\sigma_\delta}{\sigma_{\hat{x}}}\right)^2}$$
- The OLS estimator is not consistent when x has uncertainty (i.e., when $\sigma_\delta > 0$)
 - We can predict how significant the bias will be before abandoning OLS

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Lecture 31: What have we learned?

- What is orthogonal regression and when is it useful?
- What is geometric mean regression and when is it useful?
- What do the method of moments and the asymptotic behavior of OLS (as $n \rightarrow \infty$) teach about the effect of x uncertainty on slope?

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