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WHAT STARTS HERE CHANGES THE WORLD

CHE384, From Data to Decisions: Measurement, Uncertainty, Analysis, and Modeling

## Lecture 30

### Total Regression, part 1

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## Assumptions in OLS Regression

1.  $\varepsilon$  is a random variable that does not depend on  $x$  (i.e., the model is perfect, it properly accounts for the role of  $x$  in predicting  $y$ )
2.  $E[\varepsilon_i] = 0$  (the population mean of the true residual is zero); this will always be true for a model with an intercept
3. All  $\varepsilon_i$  are independent of each other (uncorrelated for the population, but not for a sample)
4. All  $\varepsilon_i$  have the same probability density function (pdf), and thus the same variance (called homoscedasticity)
5.  $\varepsilon \sim N(0, \sigma_\varepsilon)$  (the residuals, and thus the  $y_i$ , are normally distributed)
6. The values of each  $x_i$  are known exactly

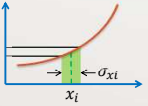
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## Uncertainty in X

- For most experiments, the predictor variable values ( $x_i$ ) are themselves the results of measurements
  - All measurements have uncertainty ( $\sigma_{xi}$ )
- If the uncertainty in each  $x_i$  has only a very small impact on the uncertainty in  $y_i$ , it may be OK to ignore it
  - For  $\hat{y}_i = f(x_i)$ , is  $\sigma_{yi} \gg \sigma_{xi} \frac{\partial f}{\partial x_i}$  for each  $i$ ?




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## Example: Hubble Constant

- Edwin Hubble noted that the rate galaxies were moving away from us was proportional to their distance from us
  - Model:  $Velocity = H_0 * Distance$
- He performed a linear regression to obtain the Hubble constant  $H_0$
- But, most of the uncertainty in his data was in the x-variable!

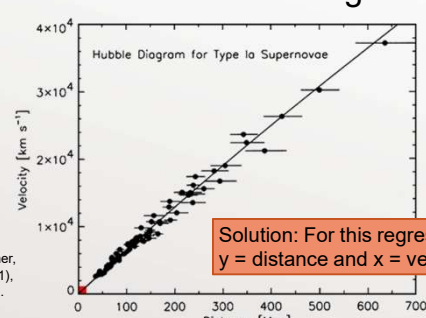


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## A Modern Hubble Diagram



R. P. Kirshner, *PNAS*, 101(1), 8-13 (2004).

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## Total Regression

- If  $X$  and  $Y$  have non-negligible uncertainty, we must find not only the predicted  $y$  values but the predicted  $x$  values as well ( $x$  and  $y$  are interchangeable)
  - Also called **Errors-in-Variables** regression or **Measurement Error Modeling** (W.A. Fuller, *Measurement Error Models*, Wiley, 2006)
  - We want values that minimize

$$S = \sum_{i=1}^n \left[ \left( \frac{\hat{y}_i - y_i}{\sigma_{yi}} \right)^2 + \left( \frac{\hat{x}_i - x_i}{\sigma_{xi}} \right)^2 \right] \quad \begin{array}{l} \hat{y}_i = \text{predicted } y \text{ value} \\ \hat{x}_i = \text{predicted } x \text{ value} \end{array}$$

- Example:  $\hat{y}_i = \beta_0 + \beta_1 \hat{x}_i$ 
  - There are  $n + 2$  best fit parameters
  - Requires a **nonlinear** least-squares regression

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## Different Total Regression Approximations

- Effective Variance Approximation
- Orthogonal Regression
- Geometric Mean
- Method of Moments
- Deming Regression
- Full Total Regression

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## Interpreting Total Regression

- **Structural Model**
  - The X's are fixed, but unknown, and so must be estimated
- **Functional Model**
  - The X's are random variables, to be represented by their mean and standard deviation (pdf)
- The difference between these two is subtle

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## Effective Variance Approximation

- We can simplify the regression for the case of **small** errors in  $x$ 
  - Let  $\hat{x}_i = x_i$
  - Define an **effective variance** in  $y$  using the model  $\hat{y}_i = f(x_i)$ :
 
$$\sigma_{yi-eff}^2 = \sigma_{yi}^2 + \left(\frac{\partial f}{\partial x_i}\right)^2 \sigma_{xi}^2$$
  - Use a **weighted** least-squares regression with weights  $w_i = 1/\sigma_{yi-eff}^2$
  - What value of  $\partial f / \partial x_i$  should we use?

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## Effective Variance Approximation

How to estimate the model slope ( $\partial f / \partial x_i$ )?

1. Run a linear regression ignoring the  $x$ -variance
2. Use this model fit to calculate  $\partial f / \partial x_i$  for each  $i$
3. Calculate the effective variance for each  $y_i$
4. Run a weighted least-squares regression using  $1/\text{effective variance}$  to weight the  $y_i$
5. Repeated steps 2-4 until the parameters converge (usually only 1-2 iterations)

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## Improving the Effective Variance

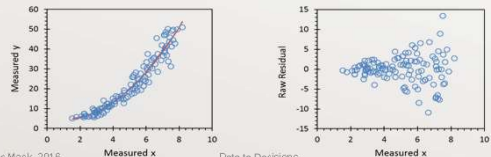
- We can also improve our estimate of  $\hat{x}_i$ 
  - For  $\hat{y}_i = f(x_i)$ ,
 
$$\hat{x}_i = x_i + \frac{(y_i - \hat{y}_i) (\partial f / \partial x_i)^2 \sigma_{xi}^2}{\sigma_{yi-eff}^2}$$
  - Again, iterate and repeat the weighted linear regression, using the better estimates for  $\hat{x}_i$  (iteratively reweighted least squares)

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## Impact of Errors in Predictor Variables

- For a straight line model, errors in  $x$  will **bias** the OLS estimate of the slope towards zero
- For a higher order model, errors in  $x$  will look like heteroscedasticity
 
$$\sigma_{yi-eff}^2 = \sigma_{yi}^2 + \left(\frac{\partial f}{\partial x_i}\right)^2 \sigma_{xi}^2$$



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## Lecture 30: What have we learned?

- When do I have to worry about error in the x-variable?
- What is total regression (also called errors-in-variables regression)?
- Explain the effective variance approximation
- How does x uncertainty affects our OLS slope estimate for a straight-line model?
- When does error in the x-variable result in heteroscedasticity?