

- (a) Can system  $S$  be time-invariant? Explain.  
 (b) Can system  $S$  be linear? Explain.  
 (c) Suppose (2) and (3) are input–output pairs of a particular system  $S_2$ , and the system is known to be LTI. What is  $h[n]$ , the impulse response of the system?  
 (d) Suppose (1) is the input–output pair of an LTI system  $S_3$ . What is the output of this system for the input in Figure P2.28-2:

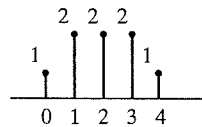


Figure P2.28-2

- 2.29. An LTI system has impulse response defined by

$$h[n] = \begin{cases} 0 & n < 0 \\ 1 & n = 0, 1, 2, 3 \\ -2 & n = 4, 5 \\ 0 & n > 5 \end{cases}$$

Determine and plot the output  $y[n]$  when the input  $x[n]$  is:

- (a)  $u[n]$   
 (b)  $u[n - 4]$   
 (c)  $u[n] - u[n - 4]$ .

- 2.30. Consider the cascade connection of two LTI systems in Figure P2.30:

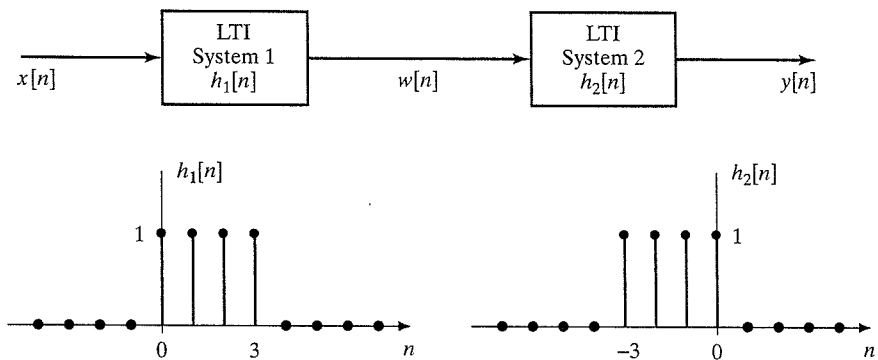


Figure P2.30

- (a) Determine and sketch  $w[n]$  if  $x[n] = (-1)^n u[n]$ . Also, determine the overall output  $y[n]$ .  
 (b) Determine and sketch the overall impulse response of the cascade system; i.e., plot the output  $y[n] = h[n]$  when  $x[n] = \delta[n]$ .  
 (c) Now consider the input  $x[n] = 2\delta[n] + 4\delta[n - 4] - 2\delta[n - 12]$ . Sketch  $w[n]$ .  
 (d) For the input of part (c), write an expression for the output  $y[n]$  in terms of the overall impulse response  $h[n]$  as defined in part (b). Make a carefully labeled sketch of your answer.