IIR Filter Design Procedure

IIR discrete-time filters are designed from analog (continuous-time) prototypes

Butterworth - monotonic in both pass/stop bands

Chebysher Type 1 - passband equiripple, stop band monotonic

Chebysher Type 2 - passband monotonic, stop band equivipple

Elliptic - equiripple in both pass/stop bands

Continuous-time filters

Differential Equations
$$H(s) = \frac{\sum_{k=0}^{n} b_k s^k}{\sum_{k=0}^{N} q_k s^k} = \frac{b_n}{a_n} \frac{\prod_{k=1}^{m} (s - c_k)}{\prod_{k=1}^{N} (s - d_k)}$$

$$h(t) = \sum_{k=1}^{N} A_k e^{d_k t} u(t)$$

Stable/causal Systems

Re{dx} < 0 ⇒ poles in left half of s-plane

- 1) Prototype low pass filter HLP(s)
- 2) Translate critical wk to 52k (prewarping)
- 3) Apply "frequency transformation" $5 = f(\tilde{s})$ $H(\tilde{s}) = H_{LP}(s)|_{s=f(\tilde{s})} \Rightarrow H(\tilde{s}) = H_{LP}(s)|_{s=f(\tilde{s})}$ so critical frequencies of $H(\tilde{s})$ are s
- 4) Use bilinear transform $S = 2 \frac{1-2^{-1}}{1+2^{-1}}$

$$H(z) = H(\tilde{z})$$

$$|\tilde{S} = 2 \frac{1 - z^{-1}}{1 + z^{-1}}$$

5) Verify that H(z) satisfies the specifications

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