

PC-HELPER

IEEE-488.2 Interface Board for PCI

**GP-IB(PCI)**

**GP-IB(PCI)L**

User's Guide

CONTEC CO.,LTD.

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# Check Your Package

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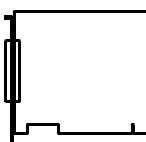
Thank you for purchasing the CONTEC product.

The product consists of the items listed below.

Check, with the following list, that your package is complete. If you discover damaged or missing items, contact your retailer.

## Product Configuration List

- Board  
[GP-IB(PCI)L or GP-IB(PCI)] ...1
- This User's Guide...1
- CD-ROM[API-PAC(W32)] ...1
- Warranty Certificate...1
- Serial number label...1



Board



User's Manual



CD-ROM  
[API-PAC(W32)]



Warranty Certificate



Serial number label

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# 1. Before Using the Product

## About the Board

This board is PCI-compliant expansion card to control GPIB devices. You can use it installing in PCI-compliant slot of your computer.

Using the bundled API function library package [API-PAC(W32)], you can create Windows application software for this board in your favorite programming language supporting Win32 API functions, such as Visual Basic or Visual C/C++.

## Features

< Common >

- Conforming to the IEEE 488.2 standard, this board can control a variety of compliant external devices.
- The product is available over an extended period of time as it uses a uPD7210-compatible GPIB controller developed by CONTEC.
- All of GPIB features can be configured by software.
- The IFC/SRQ line read feature (with IFC latch capability) is available to application programs.

< Feature of GP-IB(PCI)L >

- The timer function is available on application programs, capable of monitoring the time accurately in the Windows environment.

< Feature of GP-IB(PCI) >

- Communication can be performed at a maximum transfer rate of 1.2 megabytes per second.
- One megabyte of on-board FIFO memory for data transmission and reception allows a large amount of data to be exchanged at high speed while minimizing the effect of the PC's CPU speed.
- As FIFO memory can be used to send commands (multiline messages), a small amount of data can be exchanged at high speed as well.
- The GPIB bus analyzer function is provided to analyze data on the line.



## Support Software

You should use CONTEC support software according to your purpose and development environment.

### Driver Software Package **API-PAC(W32)** (Bundled)

API-PAC(W32) is the library software that provides the commands for CONTEC hardware products in the form of Windows standard Win32 API functions (DLL). It makes it easy to create high-speed application software taking advantage of the CONTEC hardware using various programming languages that support Win32 API functions, such as Visual Basic and Visual C/C++.

It can also be used by the installed diagnosis program to check hardware operations.

CONTEC provides download services to supply the updated drivers and differential files.

For details, read Help on the bundled CD-ROM or visit the CONTEC's Web site.

#### < Operating environment >

OS	Windows XP, 2000, NT, Me, 98, etc..
Adaptation language	Visual C/C++, Visual Basic, Delphi, Builder, etc..
Others	Each piece of library software requires 50 megabytes of free hard disk space.

### **API-GPLV(W32)** library supporting LabVIEW (Bundled)

API-GPLV(W32) is a driver created according to the National Instruments Corporation's GPIB function style. The driver is software to control the CONTEC GPIB board using a LabVIEW-based GPIB system or existing application program.

It can also be used by the installed diagnosis program to check hardware operations.

CONTEC provides download services to supply the updated drivers and differential files.

For details, read Help on the bundled CD-ROM or visit the CONTEC's Web site.

#### < Operating environment >

OS	Windows XP, 2000, NT, Me, 98, etc..
Adaptation language	LabVIEW, Visual C++, Borland C++, Visual Basic, etc..
Others	Each piece of library software requires 20 megabytes of free hard disk space.

## Cable & Connector (Option)

GPIB Cable : PCN-02 (2m)

GPIB Cable : PCN-04 (4m)

GPIB Connector : CN-GP/C

Effective when the cable being plugged into the board interfere with the PC's main unit. See the troubleshooting section at the end of Chapter 2.

Check the CONTEC's Web site for more information on these options.

# Customer Support

CONTEC provides the following support services for you to use CONTEC products more efficiently and comfortably.

## Web Site

Japanese <http://www.contec.co.jp/>  
English <http://www.contec.com/>  
Chinese <http://www.contec.com.cn/>

Latest product information

CONTEC provides up-to-date information on products.

CONTEC also provides product manuals and various technical documents in the PDF.

Free download

You can download updated driver software and differential files as well as sample programs available in several languages.

Note! For product information

Contact your retailer if you have any technical question about a CONTEC product or need its price, delivery time, or estimate information.

## Limited Three-Years Warranty

CONTEC Interface boards are warranted by CONTEC Co., LTD. to be free from defects in material and workmanship for up to three years from the date of purchase by the original purchaser.

Repair will be free of charge only when this device is returned freight prepaid with a copy of the original invoice and a Return Merchandise Authorization to the distributor or the CONTEC group office, from which it was purchased.

This warranty is not applicable for scratches or normal wear, but only for the electronic circuitry and original boards. The warranty is not applicable if the device has been tampered with or damaged through abuse, mistreatment, neglect, or unreasonable use, or if the original invoice is not included, in which case repairs will be considered beyond the warranty policy.

## How to Obtain Service

For replacement or repair, return the device freight prepaid, with a copy of the original invoice. Please obtain a Return Merchandise Authorization Number (RMA) from the CONTEC group office where you purchased before returning any product.

\* No product will be accepted by CONTEC group without the RMA number.

## Liability

The obligation of the warrantor is solely to repair or replace the product. In no event will the warrantor be liable for any incidental or consequential damages due to such defect or consequences that arise from inexperienced usage, misuse, or malfunction of this device.

# Safety Precautions

Understand the following definitions and precautions to use the product safely.

## Safety Information

This document provides safety information using the following symbols to prevent accidents resulting in injury or death and the destruction of equipment and resources. Understand the meanings of these labels to operate the equipment safely.

⚠ DANGER	DANGER indicates an imminently hazardous situation which, if not avoided, will result in death or serious injury.
⚠ WARNING	WARNING indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury.
⚠ CAUTION	CAUTION indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury or in property damage.

## Handling Precautions

### DANGER

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Do not use the product where it is exposed to flammable or corrosive gas. Doing so may result in an explosion, fire, electric shock, or failure.

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### CAUTION

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- There are switches on the board that need to be set in advance. Be sure to check these before installing the board.
  - Only set the switches and jumpers on the board to the specified settings. Otherwise, the board may malfunction, overheat, or cause a failure.
  - Do not strike or bend the board. Doing so could damage the board. Otherwise, the board may malfunction, overheat, cause a failure or breakage.
  - Do not touch the board's metal plated terminals (edge connector) with your hands. Otherwise, the board may malfunction, overheat, or cause a failure. If the terminals are touched by someone's hands, clean the terminals with industrial alcohol.
  - Do not install or remove the board to or from the slot while the computer's power is turned on. Otherwise, the board may malfunction, overheat, or cause a failure. Doing so could cause trouble. Be sure that the personal computer or the I/O expansion unit power is turned off.
  - Make sure that your PC or expansion unit can supply ample power to all the boards installed. Insufficiently energized boards could malfunction, overheat, or cause a failure.
  - The specifications of this product are subject to change without notice for enhancement and quality improvement. Even when using the product continuously, be sure to read the manual and understand the contents.
  - Do not modify the product. CONTEC will bear no responsibility for any problems, etc., resulting from modifying this product.
  - Regardless of the foregoing statements, CONTEC is not liable for any damages whatsoever (including damages for loss of business profits) arising out of the use or inability to use this CONTEC product or the information contained herein.
-

## Environment

Use this product in the following environment. If used in an unauthorized environment, the board may overheat, malfunction, or cause a failure.

Operating temperature

0 to 50°C

Humidity

10 to 90%RH (No condensation)

Corrosive gases

None

Floating dust particles

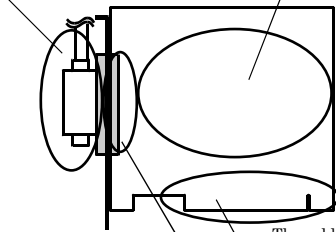
Not to be excessive

## Inspection

Inspect the product periodically as follows to use it safely.

- Check that the bus connector of the board and its cable have been plugged correctly.

- Check that the board has no dust or foreign matter adhering.



- The gold-plated leads of the bus connector have no stain or corrosion.

## Storage

When storing this product, keep it in its original packing form.

- (1) Put the board in the storage bag.
- (2) Wrap it in the packing material, then put it in the box.
- (3) Store the package at room temperature at a place free from direct sunlight, moisture, shock, vibration, magnetism, and static electricity.

## 2. Setup

This chapter explains how to set up the board.

### What is Setup?

Setup means a series of steps to take before the product can be used.

Different steps are required for software and hardware

The setup procedure varies with the OS and applications used.

### Using the Board under Windows

#### Using the Driver Library API-PAC(W32)

This section describes the setup procedure to be performed before you can start developing application programs for the board using the bundled CD-ROM “Driver Library API-PAC(W32)”.

Taking the following steps sets up the software and hardware. You can use the diagnosis program later to check whether the software and hardware function normally.

**Step 1 Installing the Software**

**Step 2 Setting the Hardware**

**Step 3 Installing the Hardware**

**Step 4 Initializing the Software**

**Step 5 Checking Operations with the Diagnosis Program**

If Setup fails to be performed normally, see the “Setup Troubleshooting” section at the end of this chapter.

## Using the Board under Window

### Using Software Other than the Driver Library

#### API-PAC(W32)

For setting up software other than API-PAC(W32), refer to the manual for that software. See also the following parts of this manual as required.

**This chapter Step 2 Setting the Hardware**

**This chapter Step 3 Installing the Hardware**

**Chapter 3 External Connection**

**Chapter 6 About Hardware**

## Using the Board under an OS Other than Windows

For using the board under an OS other than Windows, see the following parts of this manual.

**This chapter Step 2 Setting the Hardware**

**Chapter 3 External Connection**

**Chapter 6 About Hardware**

## Step 1 Installing the Software

This section describes how to install the API function libraries.

**Before installing the hardware on your PC, install the API function libraries from the bundled API-PAC(W32) CD-ROM.**

The following description assumes the operating system as Windows Me. Although some user interfaces are different depending on the OS used, the basic procedure is the same.

### About the driver to be used

Two GPIB communication drivers come with your board: API-GPIB(98/PC)W95/NT and API-GPLV(W32).

API-GPIB(98/PC)W95/NT provides a CONTEC proprietary function interface.

API-GPLV(W32) provides a function interface equivalent to that from National Instruments Corporation (hereafter NI), allowing the GPIB488, GPIB488.2, and VISA functions of LabVIEW to be used directly and application programs created for NI boards to run without modification.

Selection guide

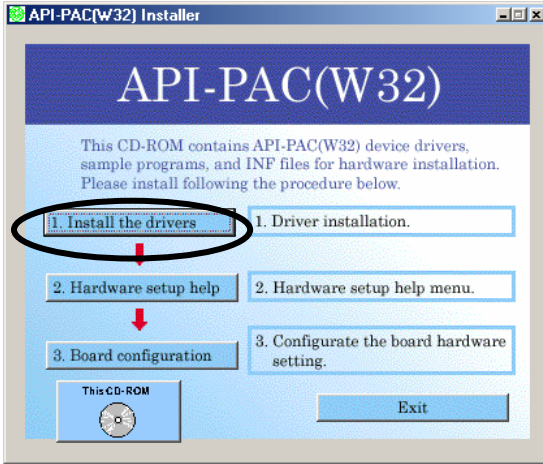
Given below is a guideline for easily selecting the appropriate driver for the board.

driver to be used	Purpose
API-GPIB(98/PC)	<ul style="list-style-type: none"> <li>- Used to use CONTEC functions</li> <li>- To make the board operate as fast as possible</li> <li>- To convert (digitize) binary and string data easily</li> </ul>
API-GPLV(W32)	<ul style="list-style-type: none"> <li>- To use existing applications for NI boards</li> <li>- To use LabVIEW</li> <li>- Familiar with NI functions but not with CONTEC functions</li> </ul>



## Starting the Install Program

- (1) Load the CD-ROM [API-PAC(W32)] on your PC.
- (2) The API-PAC(W32) Installer window appears automatically.  
If the panel does not appear, run (CD-ROM drive letter):\AUTORUN.exe.
- (3) Click on the [Install the drivers] button.



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### CAUTION

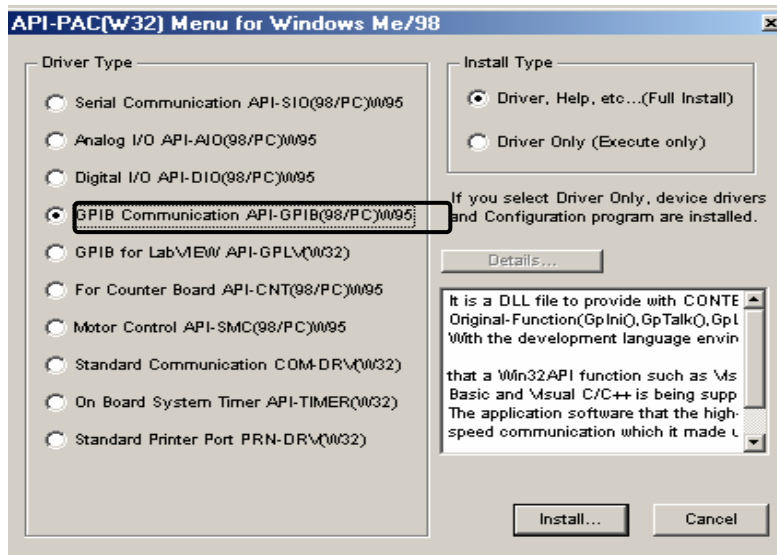
Before installing the software in Windows XP, 2000, or NT, log in as a user with administrator privileges.

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## For using API-GPIB(98/PC)xx

Select API- GPIB(98/PC)

- (1) The following dialog box appears to select “Driver Type” and “Install Type”.
- (2) Select “GPIB Communication API-GPIB(98/PC)W95”.
- (3) Select “Driver, Help, etc...(Full Install)”.
- (4) Click on the [Install] button.



### Executing the Installation

- (1) Follow the on-screen instructions to proceed to install.
- (2) When the required files have been copied, the “Perform a hardware setup now” and “Show readme file” check boxes are displayed.

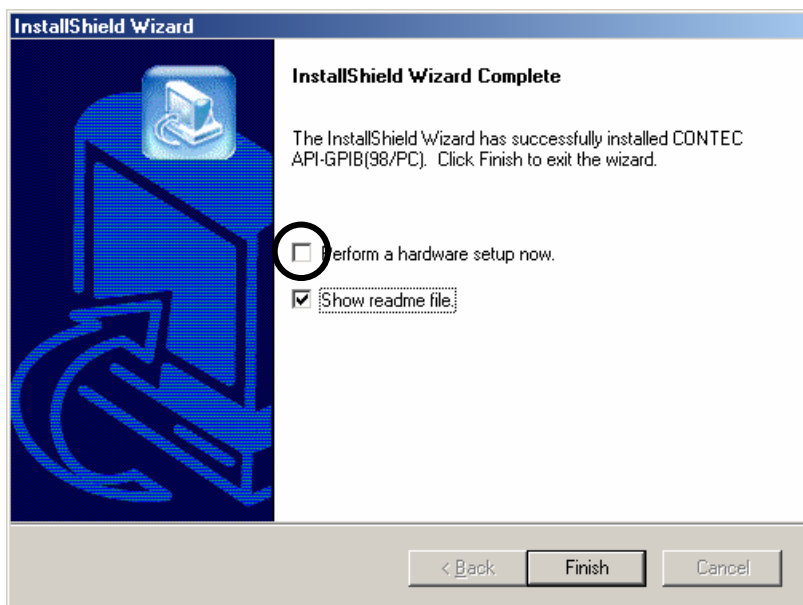
**When you are installing the software or hardware for the first time:**

**1) Uncheck “Perform a hardware setup now”.**

**2) Click on the [Finish] button. Go to Step 2 to set and plug the hardware.**

\* When the hardware has already been installed:

Check “Perform a hardware setup now”, then go to Step 4 “Initializing the Software”.

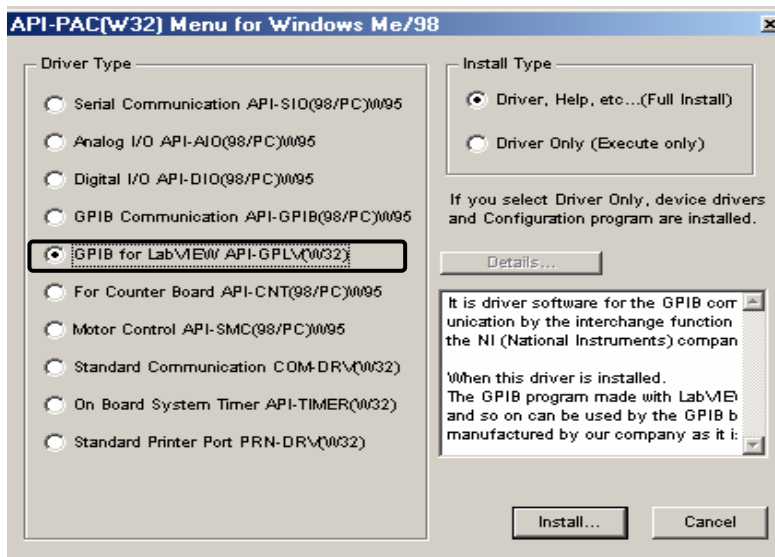


**You have now finished installing the software.**

## For using API-GPLV(W32)

Select API-GPLV(W32)

- (1) **The following dialog box appears to select “Driver Type” and “Install Type”.**
- (2) **Select “GPIB for LabVIEW API-GPLV(W32)”.**
- (3) **Select “Driver, Help, etc..(Full Install)”.**
- (4) **Click on the [Install] button.**



Executing the Installation

- (1) **Follow the on-screen instructions to proceed to install.**
  - (2) **The driver installation is completed when the GPIB setup utility is started.**  
If you are installing the software and hardware for the first time, click on the [Cancel] button in this step to terminate the installation procedure.
- \* When the hardware has already been installed:  
Go to "For Using API-GPLV(W32)" in Step 4 "Initializing the Software".

## Step 2 Setting the Hardware

This section describes how to set the board and plug it on your PC.

The board has some switches and jumpers to be preset.

Check the on-board switches and jumpers before plugging the board into an expansion slot.

The board can be set up even with the factory defaults untouched. You can change board settings later.

### Parts of the Board and Factory Defaults

Figure 2.1. to show the names of major parts on the board.

Note that the switch setting shown below is the factory default.

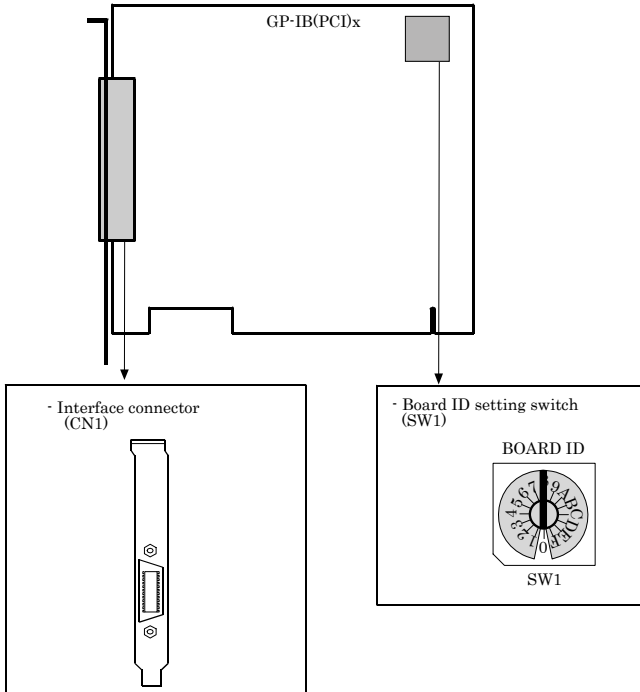


Figure 2.1. Part Names

## Setting the Board ID

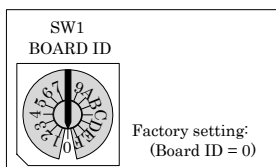
If you install two or more boards on one personal computer, assign a different ID value to each of the boards to distinguish them.

The board IDs can be set from 0 to Fh to identify up to sixteen boards.

If only one board is used, the original factory setting (Board ID = 0) should be used.

### Setting Procedure

To set the board ID, use the rotary switch on the board. Turn the SW1 knob to set the board ID as shown below.



**Figure 2.2. Board ID Settings (SW1)**

## Plugging the Board

- (1) Before plugging the board, shut down the system, unplug the power cord of your PC.
- (2) Remove the cover from the PC so that the board can be mounted.
- (3) Plug the board into an expansion slot.
- (4) Fasten the board bracket to the PC's chassis with the removed screw.
- (5) Put the cover back into place.



---

### CAUTION

- Do not touch the board's metal plated terminals (edge connector) with your hands. Otherwise, the board may malfunction, overheat, or cause a failure. If the terminals are touched by someone's hands, clean the terminals with industrial alcohol.
  - Do not install or remove the board to or from the slot while the computer's power is turned on. Otherwise, the board may malfunction, overheat, or cause a failure. Doing so could cause trouble. Be sure that the personal computer or the I/O expansion unit power is turned off.
  - Make sure that your PC or expansion unit can supply ample power to all the boards installed. Insufficiently energized boards could malfunction, overheat, or cause a failure.
-

## Step 3 Installing the Hardware

For using an expansion board under Windows, you have to let the OS detect the I/O addresses and IRQ to be used by the board. The process is referred to as installing the hardware.

In the case of using two or more boards, make sure you install one by one with the Add New Hardware Wizard.

### Turning on the PC

Turn on the power to your PC.



#### CAUTION

- The board cannot be properly installed unless the resources (I/O addresses and interrupt level) for the board can be allocated. Before attempting to install the board, first determine what PC resources are free to use.
- The resources used by each board do not depend on the location of the PCI bus slot or the board itself. If you remove two or more boards that have already been installed and then remount one of them on the computer, it is unknown that which one of the sets of resources previously assigned to the two boards is assigned to the remounted board. In this case, you must check the resource settings.

## Setting with the Add New Hardware Wizard

- (1) The “Add New Hardware Wizard” will be started.

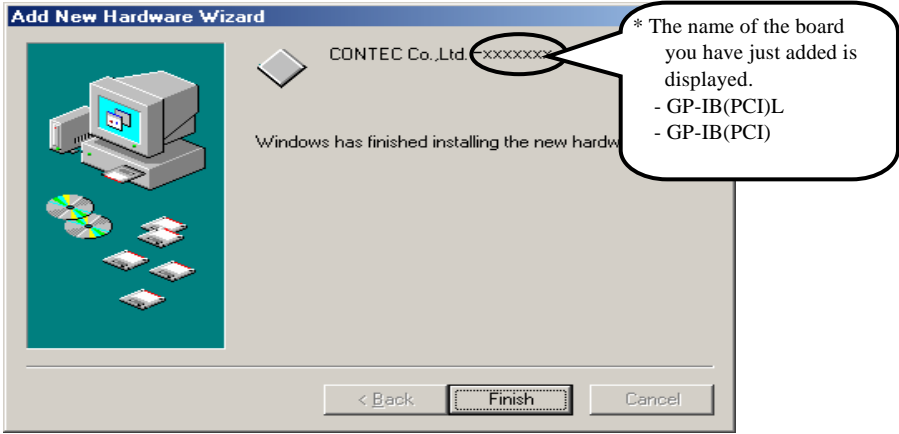
Select “Specify the location of the driver”, then click on the [Next] button.

**If you are using Windows NT 4.0, the “Add New Hardware Wizard” is not started. Go to Step 4 “Initializing the Software”.**





- (2) Specify that folder on the CD-ROM which contains the setup information (INF) file to register the board.

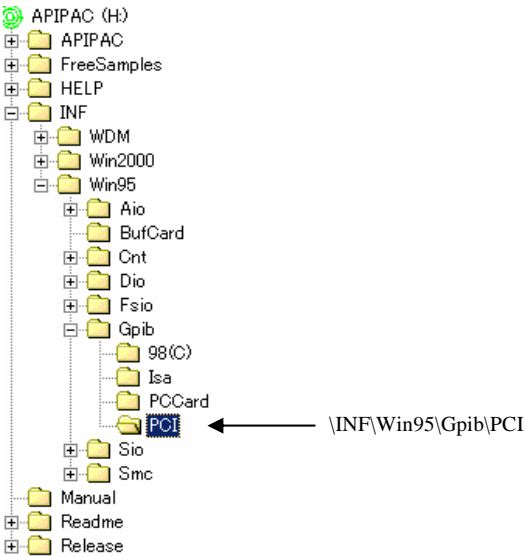


Source folder

The setup information (INF) file is contained in the following folder on the bundled CD-ROM.

Windows XP, 2000	\\INF\Win2000\Gpib\PCI
Windows Me, 98, 95	\\INF\Win95\Gpib\PCI

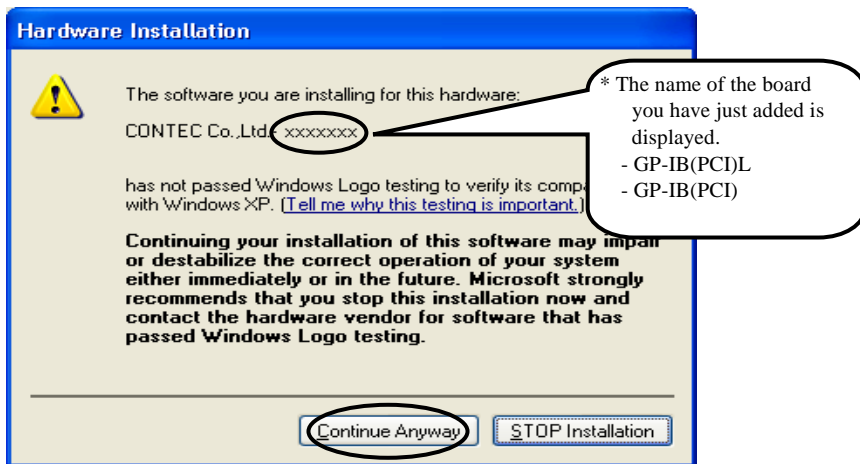
Example of specifying the folder for use under Windows Me



## ⚠ CAUTION

In Windows XP, the Hardware Wizard displays the following alert dialog box when you have located the INF file. This dialog box appears, only indicating that the relevant driver has not passed Windows Logo testing, and it can be ignored without developing any problem with the operation of the board.

**In this case, click on the [Continue Anyway] button.**



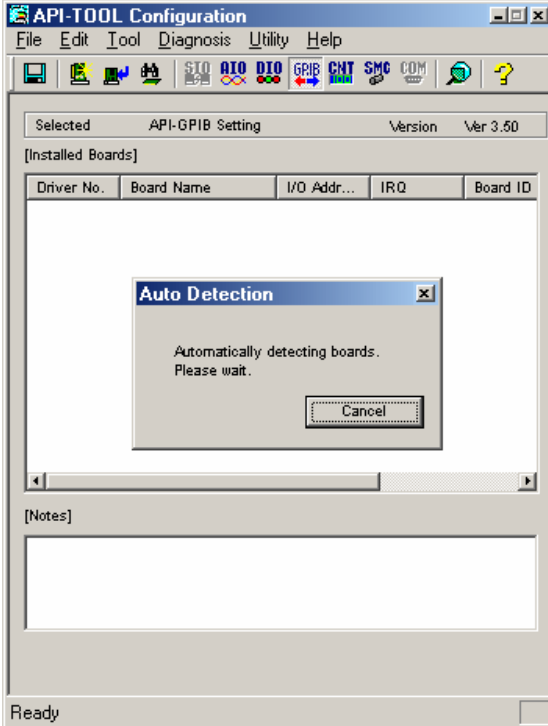
**You have now finished installing the hardware.**

## Step 4 Initializing the Software

The API function library requires the initial setting to recognize the execution environment. It is called the initialization of the API function library.

### Invoking API-TOOL Configuration

- (1) Open the Start Menu, then select “Programs” – “CONTEC API-PAC(W32)” – “API-TOOL Configuration”



- (2) API-TOOL Configuration detects boards automatically.  
The detected boards are listed.

### Updating the Settings

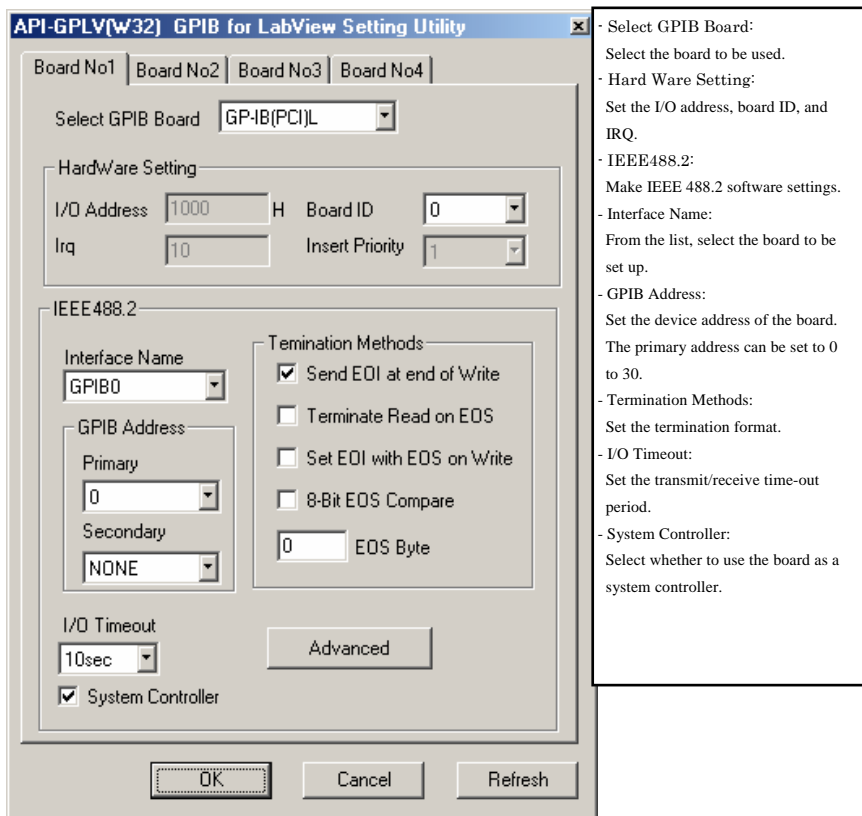
- (1) Select “Save setting to registry...” from the “File” menu.

**You have now finished installing the initial setting of Software.**

## For using API-GPLV(W32)

Invoking Configuration Utility

- (1) Open the Start Menu, then select “Programs” – “CONTEC API-PAC(W32)” – “GPLV” – “Configuration Utility”



- Select GPIB Board:  
Select the board to be used.
- Hard Ware Setting:  
Set the I/O address, board ID, and IRQ.
- IEEE488.2:  
Make IEEE 488.2 software settings.
- Interface Name:  
From the list, select the board to be set up.
- GPIB Address:  
Set the device address of the board. The primary address can be set to 0 to 30.
- Termination Methods:  
Set the termination format.
- I/O Timeout:  
Set the transmit/receive time-out period.
- System Controller:  
Select whether to use the board as a system controller.

Updating the Settings

- (1) Click on the [Refresh] button, then on the [OK] button.

**You have now finished installing the initial setting of Software.**

## Step 5 Checking Operations with the Diagnosis Program

Use the diagnosis program to check that the board and driver software work normally, thereby you can confirm that they have been set up correctly.

### What is the Diagnosis Program?

The diagnosis program diagnoses the states of the board and driver software.

It can also be used as a simple checker when an external device is actually connected.

Using the “Diagnosis Report” feature reports the driver settings, the presence or absence of the board, I/O status, and interrupt status.

### Check Method

Perform the transmit/receive test and check the execution environment with the board connected to the remote device.

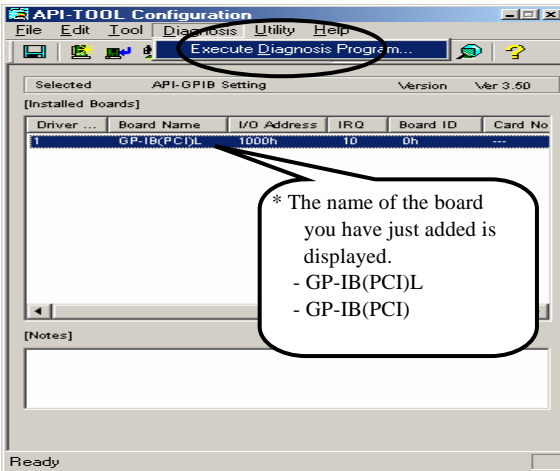
Before diagnosis, check the address of the remote device. Prepare the user’s guide and command reference for the remote device as required (to perform testing smoothly).

### Using the Diagnosis Program for Using API-GPIB(98/PC)xx

#### Starting the Diagnosis Program

Select the board in the API-TOOL Configuration windows, then run the Diagnosis Program.

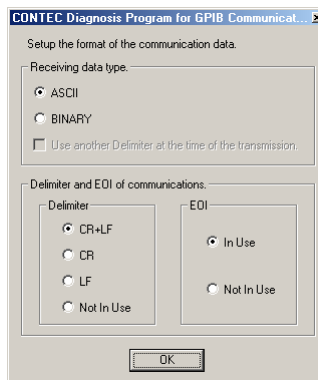
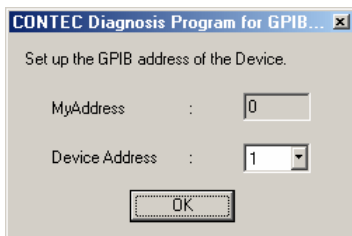
\* The name of the board you have just added is displayed.



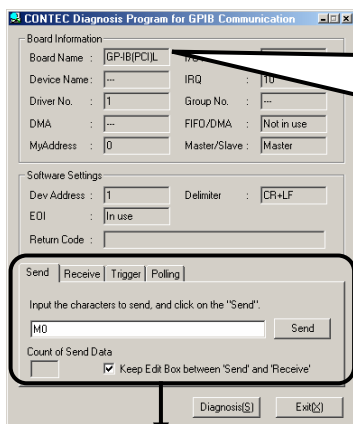
## Check of GPIB communication

The remote device address setting, communication data format setting, and main dialog boxes are displayed.

- (1) Specify the remote device address and click on the [OK] button.
- (2) Specify the communication format and click on the [OK] button.



- (3) The main dialog box appears.



\* The name of the board you have just added is displayed.  
- GP-IB(PC)I  
- GP-IB(PCI)

The following commands can be used to check GPIB operations.

“Send”: Sends the typed character string with a delimiter to the remote device.

“Receive”: Receives data from the remote device and displays it along with the number of data items.

“Trigger”: Sends a trigger command to the remote device.

“Poling”: Polls the remote device and displays the obtained status byte.

### Note

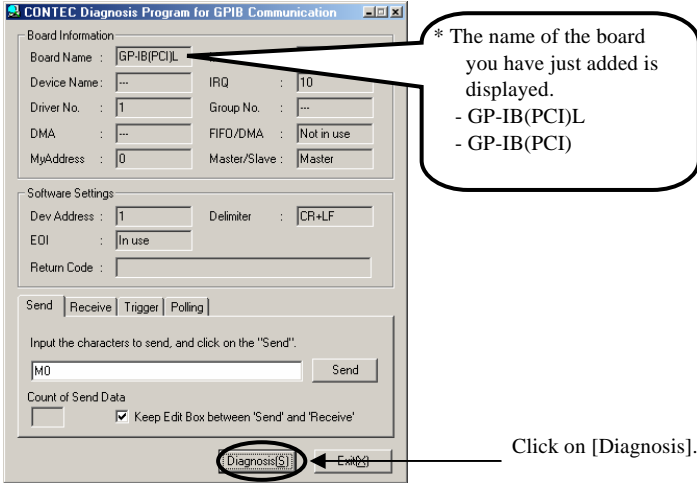
When communication has been completed successfully, “xxxxx completed normally” is displayed as the “return value”.

Diagnosis Report

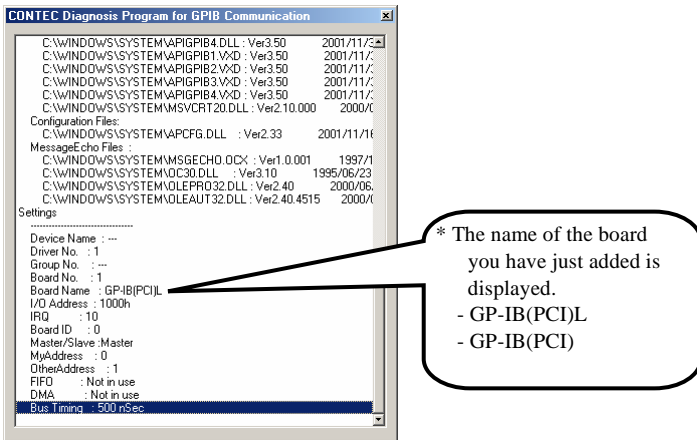
- (1) Clicking on [Diagnosis] displays detailed data including board settings and the diagnosis results while saving them in text format.

The results are saved and displayed as a text file (GpibRep.txt) in the install folder (Program Files\CONTEC\API-PAC(W32)).

The diagnosis program performs "board presence/absence check", "driver file test", "board setting test", and so on.



- (2) A diagnosis report is displayed as shown below.

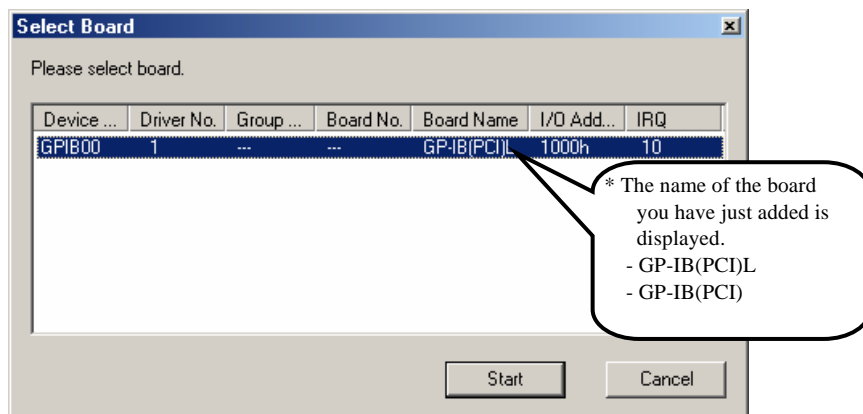


## Using the Diagnosis Program for Using API-GPLV(W32)

Starting the Diagnosis Program

Open the Start Menu, then select “Programs” – “CONTEC API-PAC(W32)” – “GPLV” – “Diagnosis Program”. Click on [Start] and follow the on-screen instructions.

\* The installed board name is displayed.

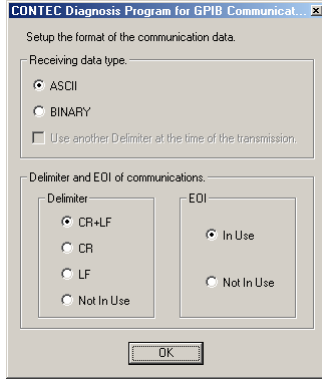
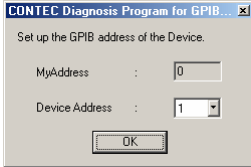




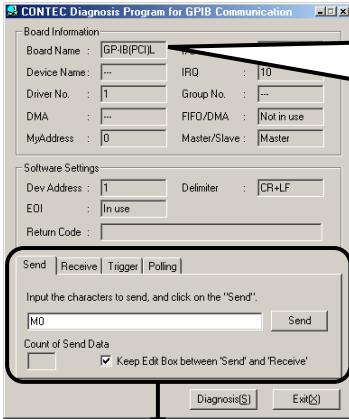
Check of GPIB communication

The remote device address setting, communication data format setting, and main dialog boxes are displayed.

- (1) Specify the remote device address and click on the [OK] button.
- (2) Specify the communication format and click on the [OK] button.



- (3) The main dialog box appears.



\* The name of the board you have just added is displayed.  
 - GP-IB(PCI)L  
 - GP-IB(PCI)

The following commands can be used to check GPIB operations.

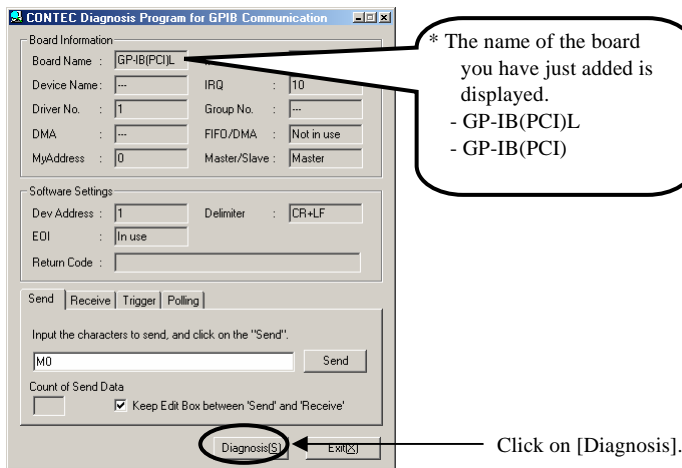
- “Send”： Sends the typed character string with a delimiter to the remote device.
- “Receive”： Receives data from the remote device and displays it along with the number of data items.
- “Trigger”： Sends a trigger command to the remote device.
- “Poling”： Polls the remote device and displays the obtained status byte.

Note

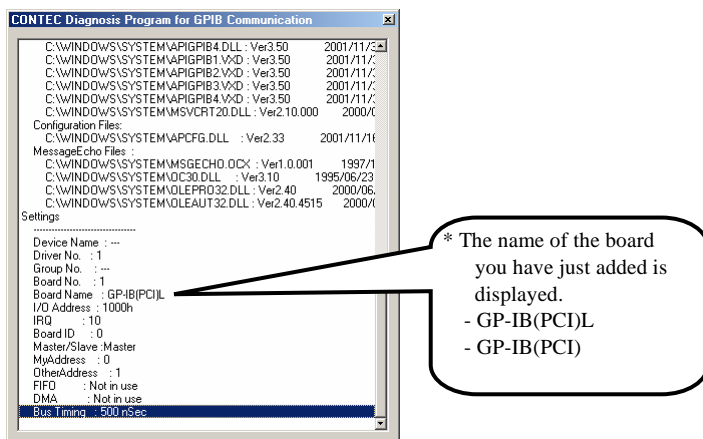
When communication has been completed successfully, “xxxxx completed normally” is displayed as the “return value”.

## Diagnosis Report

- (1) Clicking on [Diagnosis] displays detailed data including board settings and the diagnosis results while saving them in text format. The results are saved and displayed as a text file (GpibRep.txt) in the install folder (Program Files\CONTEC\API-PAC(W32)). The diagnosis program performs "board presence/absence check", "driver file test", "board setting test", and so on.



- (2) A diagnosis report is displayed as shown below.



# Setup Troubleshooting

## Symptoms and Actions

Initialization of a board cannot be performed [Windows NT4.0]

The driver may not yet be activated. If your PC is running under Windows NT 4.0, set the PnP OS option in the BIOS Setup menu to "NO".

For details on how to set up the BIOS, refer to the manual for your PC.

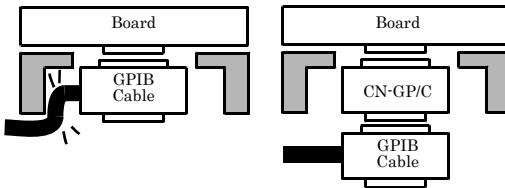
A GPIB error occurs.

The remote device address may be incorrect or the GPIB cable may not yet be connected.

The GPIB cable cannot be connected.

The GPIB cable may interfere with the chassis of your PC and not be plugged correctly into the interface connector of the board depending on the structure of your PC, for example, when the slots are located in the rear panel of the PC too deeply.

You can use the GPIB connector adapter (CN-GP/C) to work around this problem.



The OS won't normally get started or detect the board. [Windows XP, 2000]

Turn off the power to your PC, then unplug the board. Restart the OS and delete the board settings of API-TOOL Configuration. Turn off the PC again, plug the board, and restart the OS. Let the OS detect the board and use API-TOOL Configuration to make board settings over again.

## If your problem cannot be resolved

Refer to the troubleshooting section of API-GPLV HELP.

## 3. External Connection

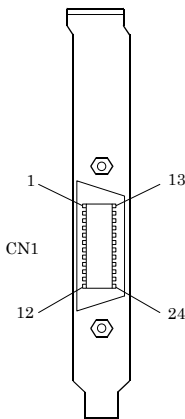
This chapter describes the interface connectors on the board and the external I/O circuits.

Check the information available here when connecting an external device.

### Using the On-board Connectors

#### Connecting a Device to a Connector

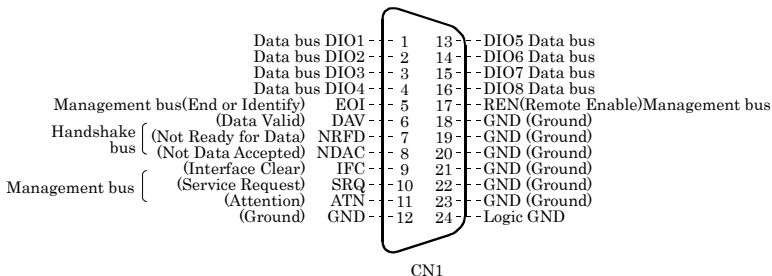
To connect an external device to this board, plug the cable from the device into the interface connector (CN1) shown below.



On-board connector : 555139-1(AMP)  
Applicable connector(cable): GPIB cable(IEEE-488 rated)

**Figure 3.1. Interface Connectors and Mating Connectors**

#### Connector Pin Assignment



CN1

**Figure 3.2. Pin Assignment of CN1**

## Notes on cable connection

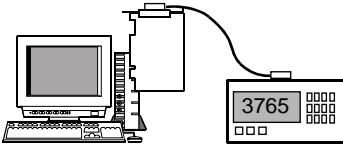
The GPIB has restrictions on the number of devices connected and the cable length according to the standard.

- (1) The maximum number of interfaces (external devices) is 15, which can be connected to one system.
- (2) The maximum total length of cables that can be used to interconnect a group of devices in one bus system is “2 m x (the number of devices)” or 20 m, whichever is shorter. (JIS C1901-1987).

Note, however, the individual cables between devices must be within 4 m long. Some examples are given below.

- System with a total of two devices  
 $2 \text{ m} \times (\text{Number of devices} = 2) < 20 \text{ m}$

The maximum total length of cables for this system is therefore 4 m.

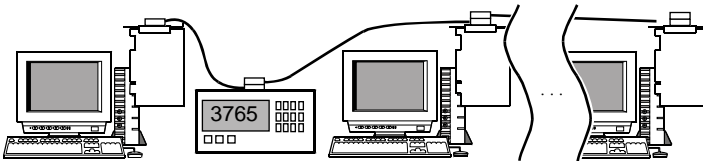


- System with a total of three devices  
 $2 \text{ m} \times (\text{Number of devices} = 3) < 20 \text{ m}$

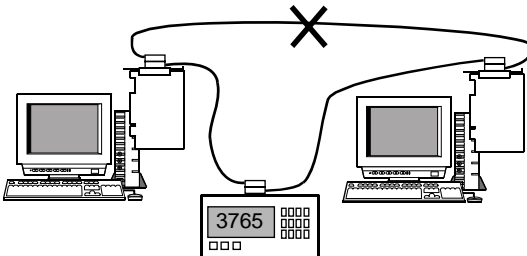
The maximum total length of cables for this system is therefore 6 m. The two cables used in the system must be [2 m + 4 m] or [2 m + 2 m] in length so that neither is longer than 4 m.

- System with a total of fifteen devices  
 $2 \text{ m} \times (\text{Number of devices} = 15) > 20 \text{ m}$

The maximum total length of cables for this system is therefore 20 m.



- (3) The cables in the system must not form a loop.



- (4) Unplug the cable from any device which is left off for some reason such as a fault.

- (5) When powering the measurement system, turn on the measuring instrument first and then on the PC.
- (6) Neither unplug/plug the cable nor turn on/off the device during communication. Doing so stops the operation or causes an error, resulting in trouble.
- (7) The talker and listener must be addressed to talk and to listen, respectively, by the controller before the talker can send messages to the listener.
- (8) At least two thirds of all the devices connected must be turned on.



## 4. Functions

This section describes the functions of the board.

### Basic GPIB Functions

#### Master/slave function

The board can serve as the master (controller) or slave depending on the setting of API-TOOL Configuration (API-GPIB(98/PC)xx) or Setup Utility (API-GLPV(W32)).

When used as the master, the board can send IFC (InterFace Clear) at any timing and control the REN (Remote ENable) line.

#### Communication function

The board can send and receive data in accordance with the IEEE 488 Standard. You can add delimiters and EOI (End of Identify) to outgoing data depending on the software settings.

#### Serial poll/parallel poll/SRQ send functions

The following functions can be used depending on the master/slave configuration.

Master

Serial poll

Parallel poll

Slave

Status byte setting

SRQ (Service ReQuest) transmission

Response to parallel polling

#### My address setting

The GPIB address (my address) of the board can be set by API-TOOL Configuration (API-GPIB(98/PC)xx) or Configuration Utility (API-GLPV(W32)). No setting is required on the board.



# Additional Functions

## Line monitor function

The board can read the current status of all control lines and handshake lines (IFC, ATN, SRQ, REN, EOI, DAV, NRFD, NDAC). It can also read latch data from the IFC line.

GPIB (PCI) can read the latch data on all control lines and the current status of the data line (DIO 1-8).

	Current status read	Latch data read
GP-IB(PCI)	All Line(IFC, ATN, SRQ, REN, EOI, DAV, NRFD, NDAC, DIO1 to DIO8)	Control line, Handshake line (IFC, ATN, SRQ, REN, EOI, DAV, NRFD, NDAC)
GP-IB(PCDL)	Control line, Handshake line (IFC, ATN, SRQ, REN, EOI, DAV, NRFD, NDAC)	Only IFC line

## Communication using FIFO memory (Only GP-IB(PCI))

The board can use on-board FIFO memory for communication. As the board controls this form of communication, it can be performed at high speed irrelevant to the PC's CPU speed.

Note, however, that the actual communication speed is set to the speed of the slowest device in compliance with the GPIB standard.

## Analyzer function (Only GP-IB(PCI))

The state transition of all lines in the GPIB cable can be analyzed by using the on-board FIFO memory. This function can be used to locate the cause of a failure or to check data flowing on lines.

The function is provided by the analyzer utility (Analyzer.exe).

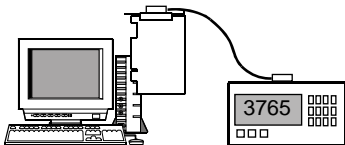
Open the Start Menu, then select “CONTEC API-PAC(W32)” – “GPIB” – “GPIB ANALYZER”. Otherwise, directly execute “Program Files\API-PAC(W32)\GPIB\ANALYZER\Analyzer.exe”.

### Running Method

- (1) Install the board on your PC according to Step 2 “Setting the Hardware” and Step 3 “Installing the Hardware” in Chapter 2 “Setup”.

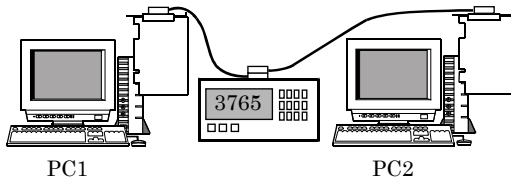
After having installed the board, connect the board to an instrument for analysis. The board can communicate with the instrument while executing analysis.

Example 1 of Connection:



One board communicating the instrument while analyzing

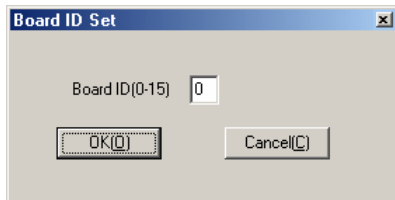
Example 2 of Connection:



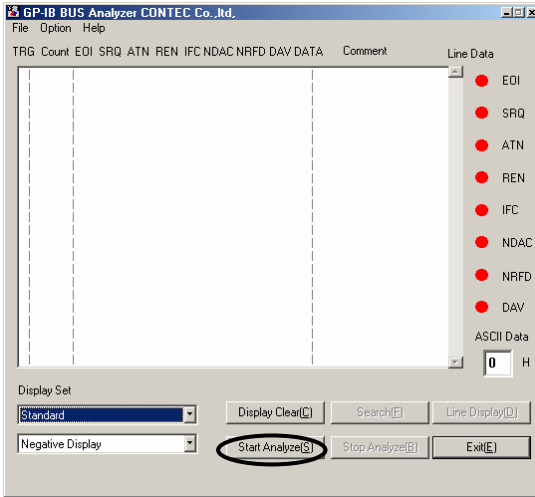
PC1: Only the analyzer is executed.

PC2: Communicating with the measuring instrument

- (2) The analyzer utility is started with the following dialog box. Enter the number of the on-board SW1 (BOARD ID) in decimal representation, then click on [OK]. The factory default of SW1 is 0.



- (3) Click on the [Start Analyze] button. The analyzer utility analyzes the subsequent changes to lines. When the communication you want to analyze has been completed, click on the [Stop Analyze] button. The analysis results will be displayed on the screen.



Convenient usage

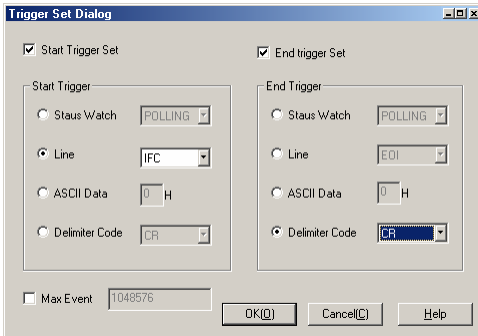
- (1) Using the start and end triggers

During analysis, the analyzer utility can obtain data only when a specific condition is satisfied in the entire session of communication. The condition that can be specified is a communication status (polling, transmit/receive, etc.), a change to the control line (EOL, SRQ, ATN, etc.), a data line match (specified ASCII code), or a delimiter match.

Select “Set Trigger Condition” from the “Set” menu.

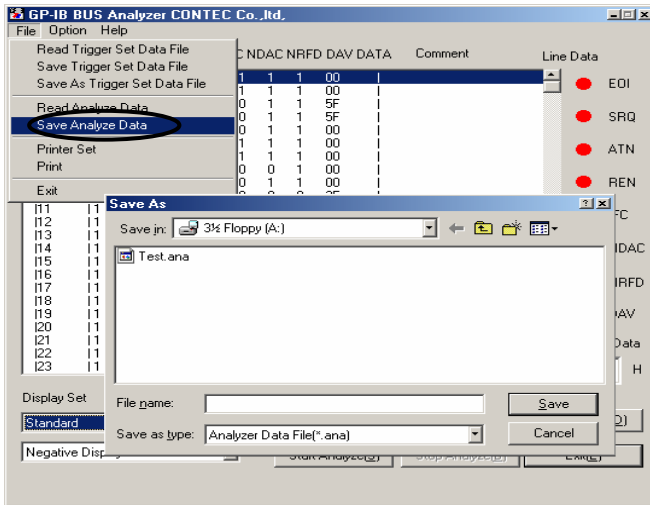
The analyzer utility works as follows with the settings made on the Trigger Set Dialog below.

- The analyzer utility starts analysis the moment IFC changes.
- The analyzer utility ends analysis upon transmit/receive of data “CR” (ODH).



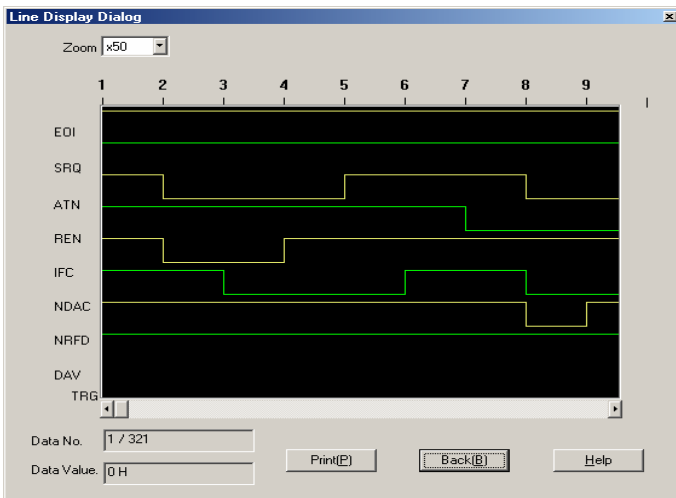
## (2) Saving analysis data

Once saved, obtained analysis data can be opened again with the analyzer utility. Since analysis data is saved in CSV format as well, you can reference and edit the data using a proper program such as Excel.



## (3) Viewing analysis data in a chart

The analysis utility can display analysis data in a chart.





## 5. About Software

The bundled CD-ROM “Driver Library API-PAC(W32)” contains the functions that provide the following features:

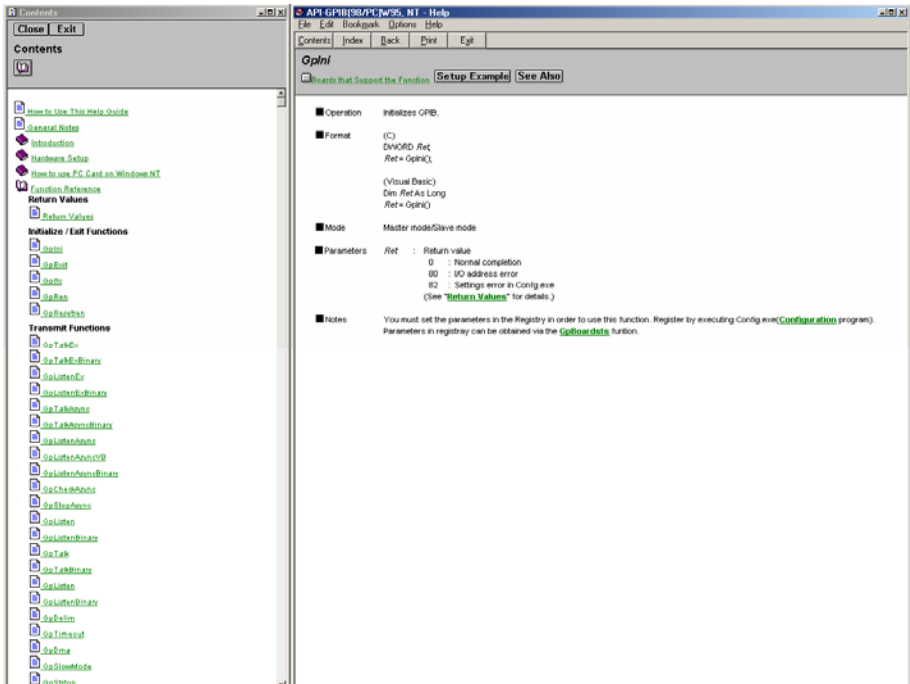
- All of the master mode, slave mode, and interrupt level can be set by software.
- Three-wire handshaking is employed to assure transfer even between the sending and receiving devices different in speed.

For details, refer to the help file. The help file provides various items of information such as “Function Reference”, “Sample Programs”, and “FAQs”. Use them for program development and troubleshooting.

## For using API-GPIB(98/PC)xx

### Accessing the Help File

- (1) Click on the [Start] button on the Windows taskbar.
- (2) From the Start Menu, select “Programs” – “CONTEC API-PAC(W32)” – “GPIB” – “API-GPIB HELP” to display help information.

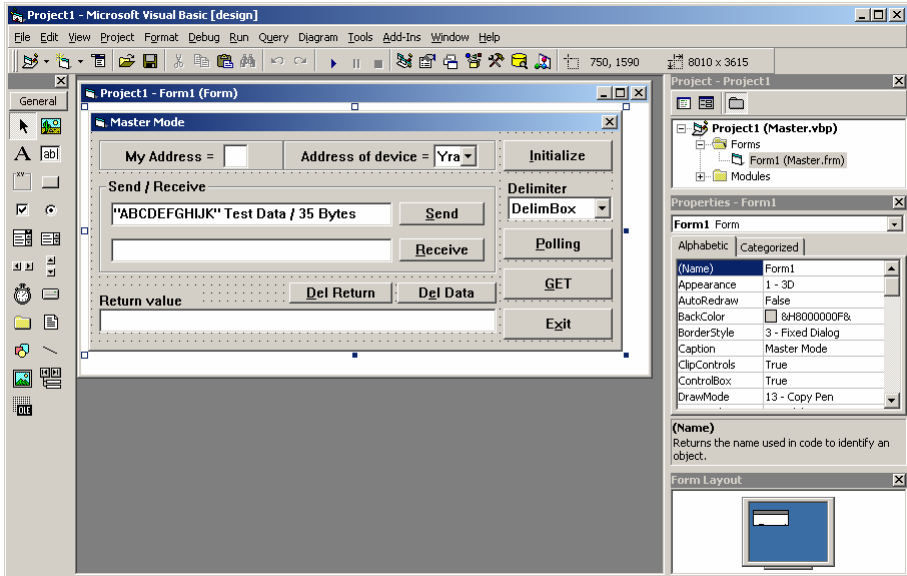


## Using Sample Programs

Bundled sample programs cover basic transmit/receive and polling in master and slave modes and support ADVANTEST Multimeters, YEW voltage generators, and SONY Tektronix oscilloscopes.

Use these sample programs as references for program development and operation check.

The sample programs are stored in \Program Files\CONTEC\API-PAC(W32)\GPIB\Samples.



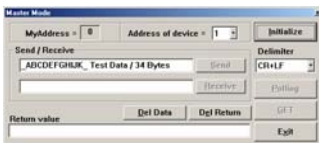
### Running a Sample Program

- (1) Click on the [Start] button on the Windows taskbar.
- (2) From the Start Menu, select “Programs” – “CONTEC API-PAC(W32)” – “GPIB” – “SAMPLE...”.
- (3) A sample program is invoked.

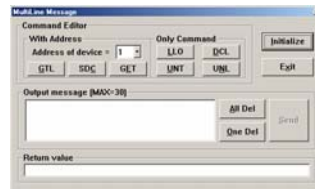
## Sample Programs - Examples

- Master Mode : Executes a series of operations in master mode.
- Slave Mode : Executes a series of operations in slave mode.
- Multi-meter : Triggers a multimeter periodically (based on the timer and events) to sample and display data.
- Voltage Source control : Allows the master to gain control of a digital voltmeter at fixed intervals.
- Oscilloscope 1 : Receives screen data from an oscilloscope and displays it in a graph.
- Oscilloscope 2 : Receives screen data from an oscilloscope and saves it in CSV format.
- MultiLine Message : Creates a multiline message for the remote device.

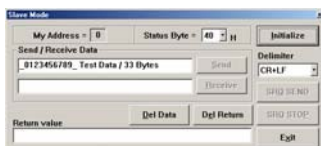
## [Master Mode]



## [MultiLine Message]



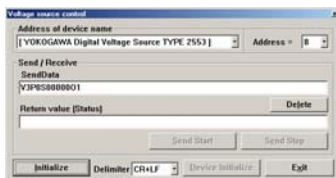
## [Slave Mode]



## [Oscilloscope 2]



## [Voltage Source control]





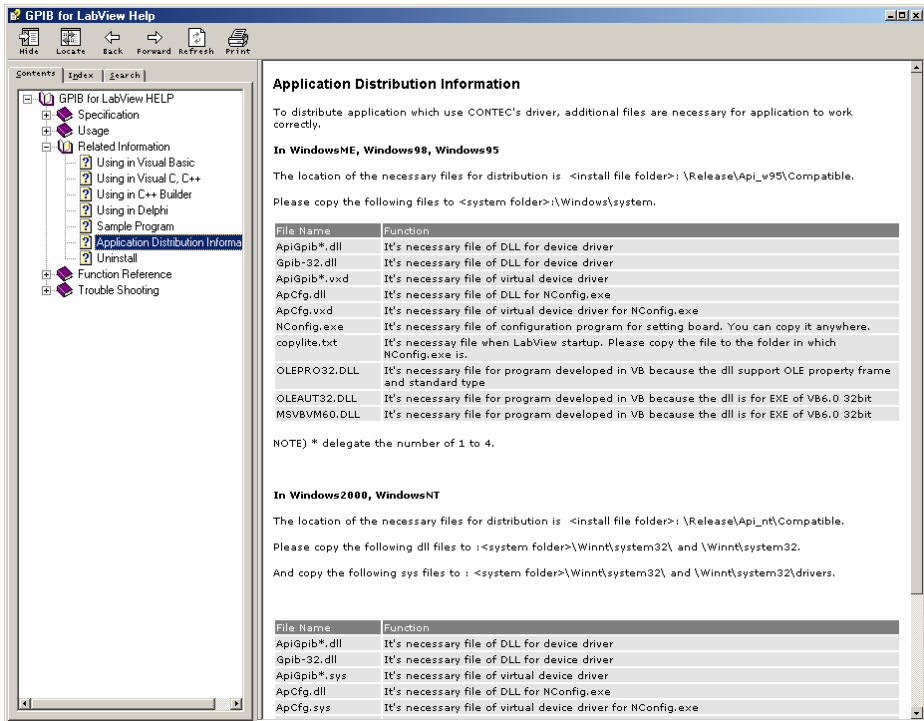
# For using API-GPLV(W32)

API-GPLV(W32) is a driver created in NI's GPIB function style as the software for controlling CONTEC GPIB boards.

When the driver is installed, existing applications such as LabVIEW can operate CONTEC GPIB boards. For details, refer to the help file. The help file provides information such as "operation specifications", "additional information", and "troubleshooting".

## Accessing the Help File

- (1) Click on the [Start] button on the Windows taskbar.
- (2) From the Start Menu, select "Programs" – "CONTEC API-PAC(W32)" – "GPLV" – "API-GPLV HELP" to display help information.



## Function List

Up to now the NI-488.2 Board-Level Calls

Function Name	Action Outline
ibask	Return information about software configuration parameters.
ibcac	Become Active Controller.
ibcmd	Send GPIB commands.
ibcmda	Send GPIB commands asynchronously.
ibconfig	Change the software configuration parameters.
ibdma	Enable or disable DMA.
ibeos	Configure the end-of-string (EOS) termination mode or character.
ibeot	Enable/disable auto-assertion of GPIB EOI line at the end of write.
ibfind	Open and initialize a GPIB board.
ibgts	Go from Active Controller to Standby.
ibist	Set or clear the board individual status bit for parallel polls.
iblines	Return the status of the eight GPIB control lines.
ibln	Check for the presence of a device on the bus.
ibloc	Go to local.
ibnotify	Asynchronously notify user when one or more GPIB events occur.
ibonl	Place the device online or offline.
ibpad	Change the primary address.
ibppe	Parallel poll configure.
ibrd	Read data from a device into a user buffer.
ibrda	Read data asynchronously from a device into a user buffer.
ibrdf	Read data from a device into a file.
ibrpp	Conduct a parallel poll.
ibrsc	Request or release system control.
ibrsv	Request service and change the serial poll status byte.
ibsad	Change or disable the secondary address.
ibsic	Assert IFC (Interface Clear).
ibstre	Set or clear the Remote Enable (REN) line.
ibstop	Abort asynchronous I/O operation.
ibtmo	Change or disable the I/O timeout period.
ibwait	Wait for GPIB events.
ibwrt	Write data to a device from a user buffer.
ibwrt a	Write data asynchronously to a device from a user buffer.
ibwrt f	Write data to a device from a file.

### Up to now the Ni-488.2 Device-Level Calls

---

<b>Function Name</b>	<b>Action Outline</b>
ibask	Return information about software configuration parameters.
ibbna	Change the access board of a device.
ibclr	Clear a specific device.
ibconfig	Change the software configuration parameters.
ibdev	Open and initialize a device
ibeos	Configure the end-of-string (EOS) termination mode or character.
ibeot	Enable/disable auto-assertion of GPIB EOI line at the end of write.
ibln	Check for the presence of a device on the bus.
ibloc	Go to local.
ibnotify	Asynchronously notify user when one or more GPIB events occur.
ibonl	Place the device online or offline.
ibpad	Change the primary address.
ibpct	Pass control to another GPIB device with Controller capability.
ibppe	Parallel poll configure.
ibrd	Read data from a device into a user buffer.
ibrda	Read data asynchronously from a device into a user buffer.
ibrdf	Read data from a device into a file.
ibrpp	Conduct a parallel poll.
ibrsp	Conduct a serial poll.
ibsad	Change or disable the secondary address.
ibstop	Abort asynchronous I/O operation.
ibtmo	Change or disable the I/O timeout period.
ibtrg	Trigger selected device.
ibwait	Wait for GPIB events.
ibwrt	Write data to a device from a user buffer.
ibwrta	Write data asynchronously to a device from a user buffer.
ibwrtf	Write data to a device from a file.

## NI-488.2 Calls for Multiple Devices

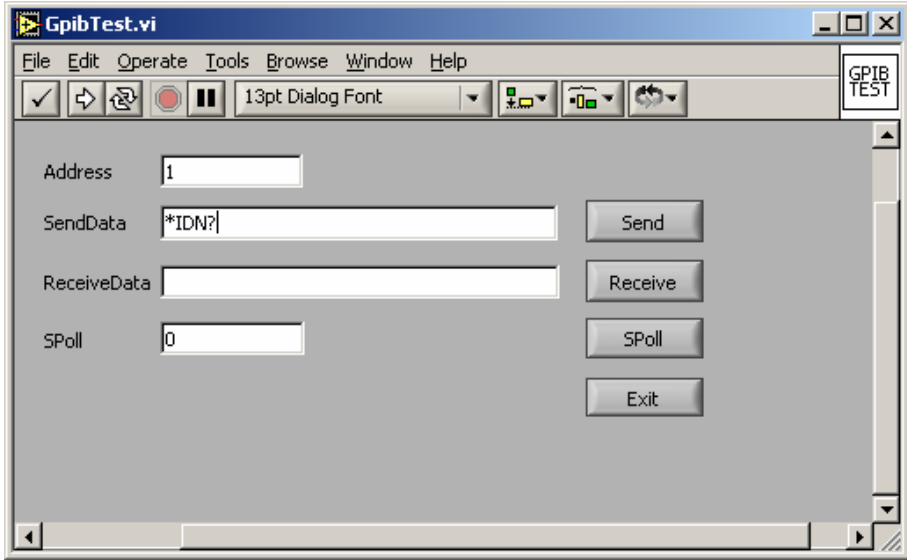
<b>Function Name</b>	<b>Action Outline</b>
AllSpoll	Serial poll all devices.
DevClear	Clear a single device.
DevClearList	Clear multiple devices.
EnableLocal	Enable operations from the front panel of deceives (leave remote programming mode).
EnableRemote	Enable remote GPIB programming for devices.
FindListn	Find listening devices on the GPIB.
FindRQS	Determine which device is requesting service.
PassControl	Pass control to another device with Controller capability.
PPoll	Perform a parallel poll on the GPIB.
PPollConfig	Configure a device to respond to parallel polls.
PPollUnconfig	Unconfigure devices for parallel polls.
RcvRespMsg	Read data bytes from a device that is already addressed to talk.
ReadStatusByte	Serial poll a single device.
Receive	Read data bytes from a device.
ReceiveSetup	Address a device to be a Talker and the interface board to be a Listener in preparation for RcvRespMsg.
ResetSys	Reset and initialize IEEE 488.2-compliant devices.
Send	Send data bytes to a device.
SendCmds	Send GPIB command bytes.
SendDataBytes	Send data bytes to devices that are already addressed to listen.
SendFC	Reset the GPIB by sending interface clear.
SendList	Send data bytes to multiple GPIB devices.
SendLLO	Send the Local Lockout (LLO) message to all devices.
SendSetup	Set up devices to receive data in preparation for SendDataBytes.
SetRWLS	Place devices in Remote With Lockout State.
TestSRQ	Determine the current state of the GPIB Service Request (SRQ) line.
TestSys	Cause IEEE 488.2-compliant devices to conduct self-test.
Trigger	Trigger a device.
TriggerList	Trigger multiple devices.
WaitSRQ	Wait until a device asserts the GPIB Service Request (SRQ) line.

## Using Sample Programs

Sample programs can execute basic transmit/receive and polling.

Use these sample programs as references for program development and operation check.

The sample programs are stored in \Program Files\CONTEC\API-PAC(W32)\GPLV\Samples.

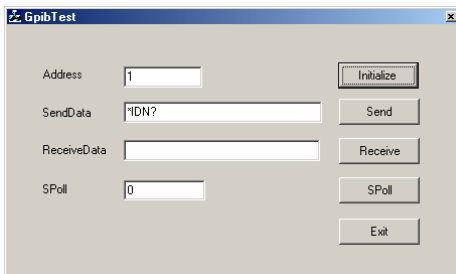


### Running a Sample Program

- (1) Click on the [Start] button on the Windows taskbar.
- (2) From the Start Menu, select “Programs” – “CONTEC API-PAC(W32)” – “GPLV” – “SAMPLE GPLV”.
- (3) A sample program is invoked.

### Program example

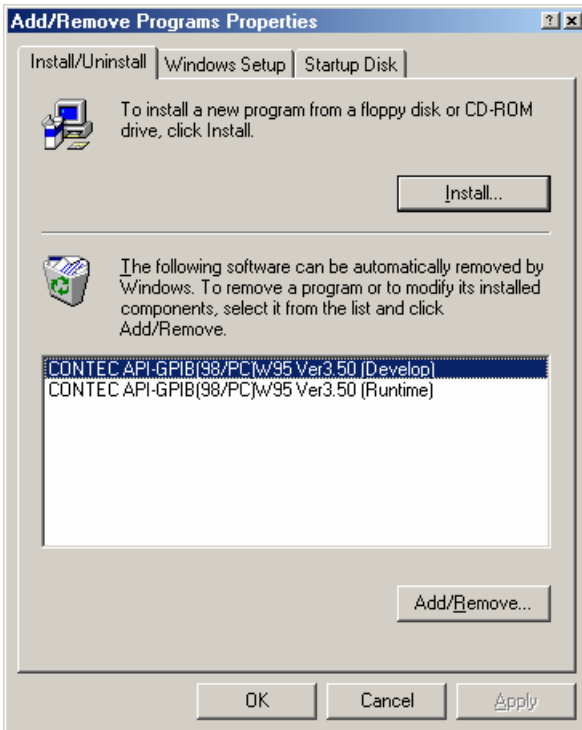
-GpibTest : Executes initialization, transmission, reception, and polling.



## Uninstalling the API Function Libraries

To uninstall API-PAC(W32), follow the procedure below.

- (1) Click on the [Start] button on the Windows taskbar. From the Start Menu, select “Settings” – “Control Panel”.
  - (2) Double-click on “Add/Remove Programs” in the Control Panel.
  - (3) Select “CONTEC API-GPIB(98/PC)xx VerX.XX (xxxx)” or “CONTEC API-GPLV(W32) VerX.XX (xxxx)”.
- [Add/Remove] button. Follow the on-screen instructions to uninstall the function libraries.



# CD-ROM Directory Structure

```
\
| Autorun.exe           Installer Main Window
| Readmeu.htm          Version information on each API-TOOL
| - APIPAC
| | - AIO
| | | - Disk 1
| | | - Disk 2
| | | - .....
| | | - Disk N
| | - CNT
| | - .....
| - FreeSamples        Sample programs in Delphi and Builder
| | - Builder 1.0
| | - .....
| - HELP              HELP file
| | - Aio
| | - Cnt
| | - .....
| - INF               OS-specific INF file folder(Windows 9X, 2000)
| | - WDM
| | - Win2000
| | - Win95
| - Manual            Reference Manual(PDF type)
| - Readme            Driver readme file folder
| - Release           Driver file(For creation of a user-specific install program)
| | - API_NT
| | - API_W95
```

## 6. About Hardware

This chapter provides hardware specifications and hardware-related supplementary information.

### Hardware specification

The following tables list the hardware specifications of the board.

GP-IB(PCI)L

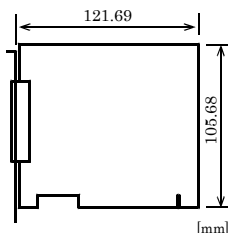
**Table 6.1. Specification <GP-IB(PCI)L>**

Item	Specifications
Number of channel	1 channel Conforms to IEEE-488.1, 488.2(GPIB)standards
Transfer format	8-bit parallel, 3-wire handshake system
Transfer rate	120Kbyte/sec (Max.)
Signal logic	Negative logic L level : 0.8V or less H level : 2.0V or more
Interrupt	1 level use
Total cable length	20m or less
Cable length between device	4m or less *1
Connectable number of device	15 devices (Max.)
I/O address	Any 32-byte boundary
Consumed current	+5VDC 300mA (Max.)
Operating conditions	0 to 50°C, 10 to 90%RH (No condensation)
PCI bus specification	32-bit, 33MHz, 5V
External dimensions (mm)	121.69(L) × 105.68(H) *2
Weight	110g

\*1 For details, see item (2) in Chapter3, "Connecting Cables".

\*2 Boards with different board numbers are different in these specifications. See Table 6.4 "Different in the specification" at the end of this document.

#### Board Dimensions



The standard outside dimension (L) is the distance from the end of the board to the outer surface of the slot cover.



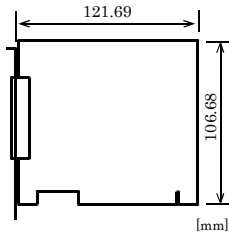
## GP-IB(PCI)

**Table 6.2. Specification <GP-IB(PCI)>**

Item	Specifications
Number of channel	1 channel Conforms to IEEE-488.1, 488.2(GPIB)standards
Transfer format	8-bit parallel, 3-wire handshake system
Transfer rate	1.2Mbyte/sec (Max.)
Capacity of transmission/receiving data	1Mbyte
Signal logic	Negative logic L level : 0.8V or less H level : 2.0V or more
Interrupt	1 level use
Total cable length	20m or less
Cable length between device	4m or less *1
Connectable number of device	15 devices (Max.)
I/O address	Any 16-byte boundary
Consumed current	+5VDC 970mA (Max.)
Operating conditions	0 to 50°C, 10 to 90%RH(No condensation)
PCI bus specification	32-bit, 33MHz, 5V
External dimensions (mm)	121.69(L) × 106.68(H)
Weight	130g

\*1 For details, see item (2) in Chapter3, "Connecting Cables".

## Board Dimensions



The standard outside dimension (L) is the distance from the end of the board to the outer surface of the slot cover.

**Table 6.3. Interface function**

Code	Function
SH1	Source handshake functions
AH1	Acceptor handshake functions
T6	Basic talker, serial polling, MLA talker release
L4	Basic listener MTA listener release
TE0	No extended talker functions
LE0	No extended listener functions
SR1	Service request function
RL1	Remote function
DC1	Device clear function
DT1	Device trigger function
PP1	Configuration by remote message
C1	System controller function
C2	IFC send, controller in-charge
C3	REN send
C4	Response to SRQ
C26	Interface message send, parallel polling

## Different in the specification

The GP-IB(PCI)L is different in specifications, depending on the board number as listed below.

**Table 6.4. Different in the specification**

### ■GP-IB(PCI)L

Board No.	No. 7169	No. 7169A
Dimension (mm)	121.69(L) × 106.68(H)	121.69(L) × 105.68(H)

# GP-IB(PCI)L GP-IB(PCI) User's Guide

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